

# PRECISION ENGINE LATHE OPERATION MANUAL & PARTS LIST

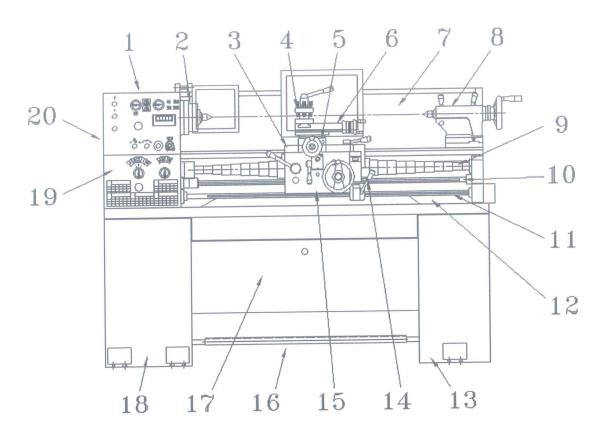
# 1340VS



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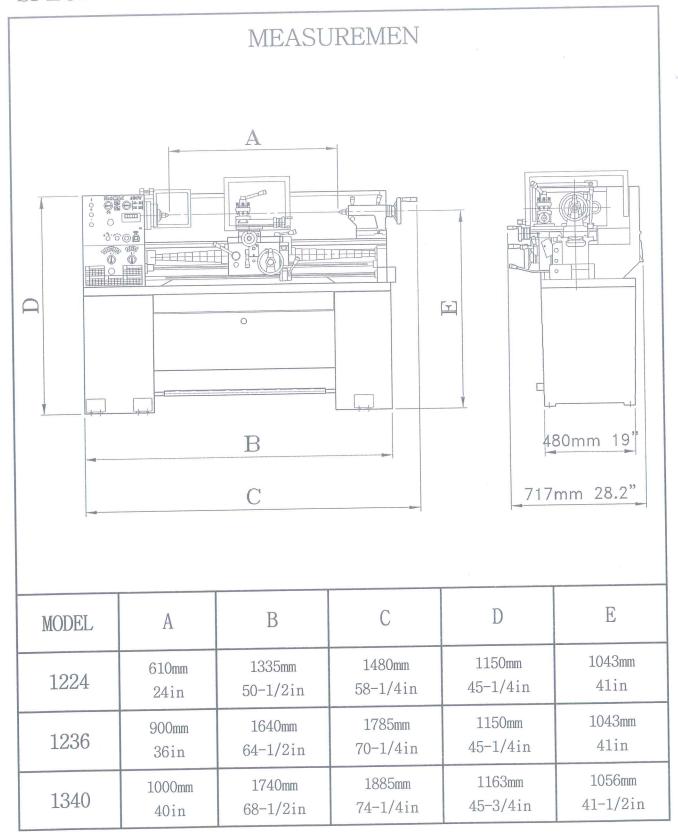
#### GENERAL LAYOUT OF LATHE



- 1. Headstock
- 2. Spindle
- 3. Saddle
- 4. Toolpost
- 5. Cross-slide
- 6. Compount-rest (Top slide)
- 7. Splash Guard
- 8. Tailstock
- 9. Lead screw
- 10. Feed road

- 11. Switch control road
- 12. Bed
- 13. Stand
- 14. Spindle rotation lever
- 15. Apron
- 16. Footbrake
- 17. Cabinet (Tool box)
- 18. Head end stand
- 19. Geadbox
- 20. End cover

		1224	1236	1340	
MODEL	CICIO	1224	1250		
NOMINAL		306m	m 12in	330mm 13in	
Swing over		186mm	7-5/16in	210mm 8-5/16in	
	Cross Slide	150mi		165mm 6-1/2in	
Height of C	etween Centers	610mm 24in	1000mm 40in		
BED	etween centers	OT OAAAAA			
Width of B	edways				
Total Leng		1220mm 48in	1525mm 60in	1625mm 64in	
	Swing over Gap	445mm 17-1/2in 470mm 18-			
G . T	Length of gap		240mm 9-1/2in		
Gap Type	Width in front of		150mm 6in		
	face plate		130111111 0111		
SPINDLE			D1-4 CAMLOCK		
The second liverage and the se	se mounting		D1-4 CAMLOCK 40mm 1-9/16in		
Spindle bo					
Taper of sp		M.T.#5  Variable speed change			
	spindle speeds		40-2000 R.P.M.		
The second liverage was a second liverage with the second liverage was a second live	pindle speeds		70 2000 10.1.111		
TOOL SLI	el of cross slide	170mm 6-3/4in			
	el of top slide	90mm 3-1/2in			
	cutting tool	13mm 1/2in			
TAIL STO					
	el of tailstock barrel	100mm 4in			
	nilstock barrel	M.T.#3			
Diameter (			40mm 1-9/16in		
THREAD					
Lead screv	w diameter & pitch	Dia. 22mm 7/8in Pitch: 4mm 8 T.P.I.			
Inch threa	ds	3-24 T.P.I. (8Nos) for metric system			
		2-56 T.P.I. (34Nos) for inch system 0.5-10 mm (21Nos) for metric system			
Metric pit	ches	0.5-10 mm (21Nos) for metric system 0.5-12mm (33Nos) for inch system			
			0.0 1211111 (001,00) 101 1110110		
FEEDS		Dia. 19mm 3/4in			
Feed rod					
	Longitudinal feeds 0.0016-0.0460in/rev. (25) for inch system				
Cross feed	ds	0	.0005-0.0150in/rev. for inch	system	
MOTOR			1.47kW		
Main spindle motor		2HP	3HP 2.2kW		
Coolant pump motor		1/8HP 0.1Kw			
	net weight	500kgs	550kgs	600kgs	
Machine net weight		620kgs	670kgs	720kgs	



#### STANDARD ACCESSORIES

Electrical equipment &		
Motor 3 Hp, 3 PH	1	set
Set of change gears	1	set
Center sieeve M.T.No. 5x3		
Two centers M.T.No. 3		
Threading dial indicator	1	set
Toolbox; set of spanners & Keys		
4-ways turret toolpost	1	pc.
Toolpost wrench	1	set
6inch(150mm) dia. backplates	1	рс.

#### OPTIONAL ACCESSORIES

3-jaw scroll chuck 6inch (150mm)
4-jaw independent chuck 8inch (200mm)
Face plate 10inch (250mm)
Steady rest
Follow rest
Coolant pump equipment
Splash guard
Single carriage stop
Taper turning attachment
American toolpost
Micro carriage stop

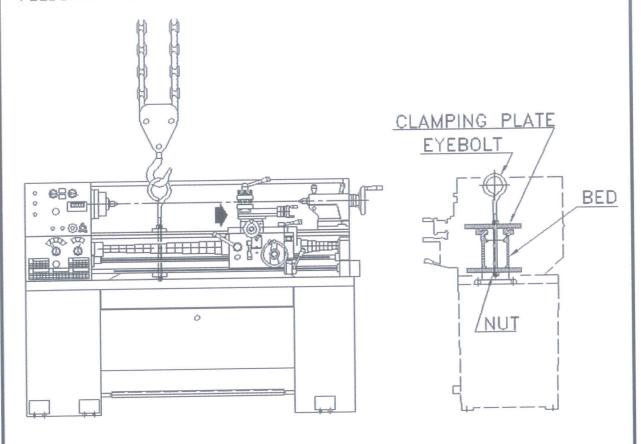
# INSTALLATION

#### LIFTING

Use the sling—chain to sling lathe showed as in figure, position the saddle and tailstock along the bed to obtain balance.

Raising and lowering the machine should be done carefully, especially when you lower the machine, be sure not to bump the machine against the floor.

IMPORTANT: DO NOT USE SLINGS AROUND BED AS LEADSCREW AND FEEDSHAFT MAY BE BENT.



#### CLEANING

Before operating and controls, use white spirit or kerosene to remove the anticorrosion coating from all slideways and the endgear train.

DO NOT USE CELLULOSE SOLVENTS FOR CLEANING AS THEY WILL DAMAGE THE PAINT FINISH.

Machine surface becomes bright immediately after cleaning using machine oil or slideway lubricant. Use heavy oil or grease on the end gears.

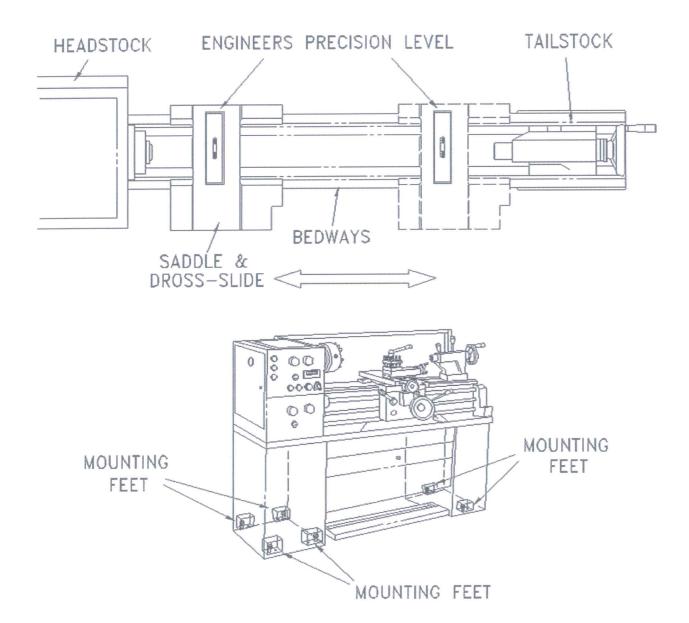
# INSTALLATION

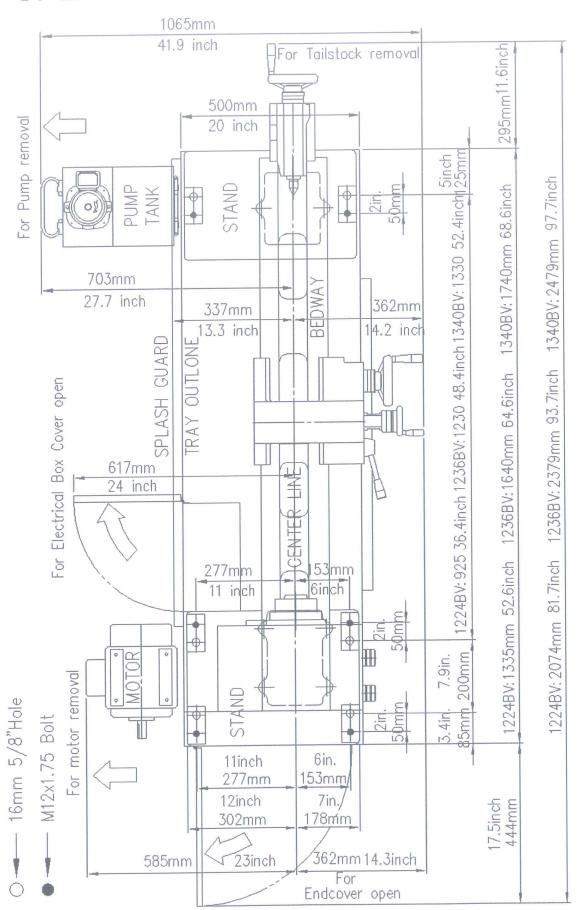
#### INSTALLING

Located the machine on a solid foundation, allowing sufficient area all round for easy working and maintenance (see Foundation Plan). The lathe maybe used free—standing or bolted to the foundation.

Free-standing: Position lathe on foundation and adjust each of the six mounting feet to take equal share of the load. Then using an engineers precision level on the bedways (as in Figure) adjust the feet to level up machine. Periodically check bed level to ensure continued Lathe accuracy.

Fixed installation: Position lathe over six bolts ( 1/2 in. or 12 mm. diam.), set into the foundation to correspond with holes in the mounting feet. Accurately level the machine as in Figure, then tighten hold—down bolts and recheck bed level.





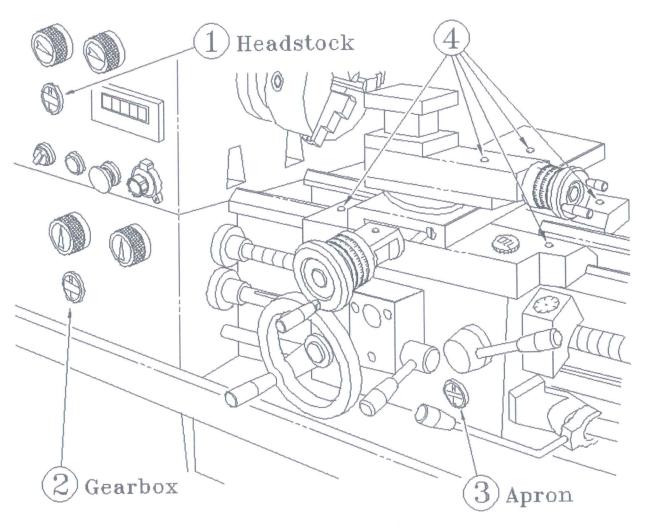
# **FOUNDATION PLAN**

# INSTALLATION

# LUBRICATION CHECKS

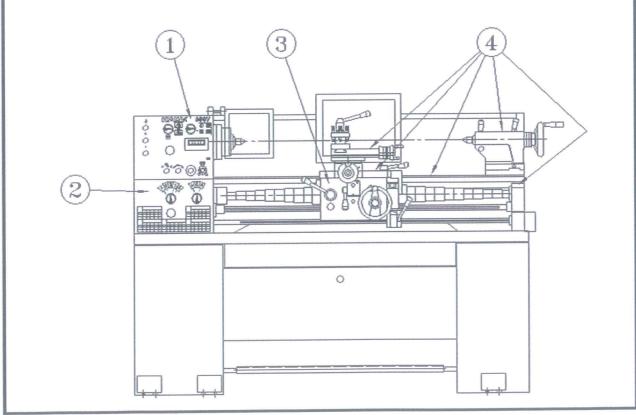
Before operating the machine make the following important checks:

- 1. That the headstock is filled to level marked on oil sight window with Shell Tellus Oil 27.
- That the gearbox filled to level marked on oil sight window with Shell Tellus Oil 27.
- That the carriage apron is filled to level mark on oil sight window with Shell Tonna 33.
- 4. In addition, apply an oil can to the points shown on lubrication diagram which require daily oiling. Use light machine oil or way lubricant.

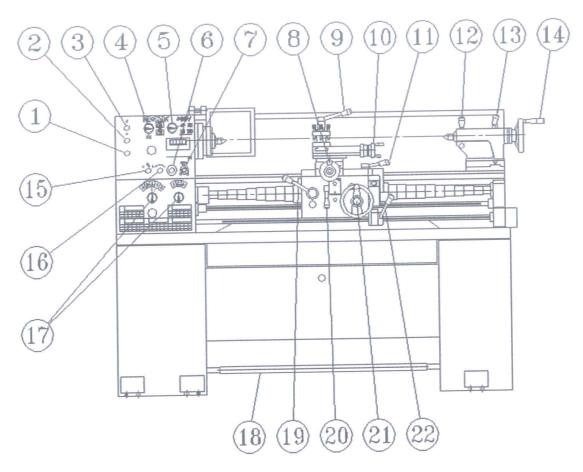


# MAINTENIANCE

SE	RVICING	AND	MAINTE	NANCE	
Part to be lubricated		1	2	3	4 SLIDE
		HEADSTOCK	GEARBOX	APRON	& TAILSTOCK
Recommendable lubricant		SHELL; TELLUS OIL 27	SHELL; TELLUS OIL 27	SHELL; TELLUS OIL 33	SHELL; TELLUS OIL 33 ~ 41
Filling method		OIL JUG	OIL JUG	OIL JUG	OIL GUN
Initial charge quantity		4.5 liter	1.5 liter	0.9 liter	
dn	Interval	3 Month	3 Month	1 Month	1 Day
Make	Quantity	0.5 liter	0.5 liter	0.2 liter	A little
ange	Interval	1 Year	1 Year	1 Year	
Exchange	Quantity	4.5 liter	1.5 liter	0.9 liter	
(1) (3) (4)					



# LATHE CONTROL



- 1. Power switch ON
- 2. Power switch OFF
- 3. Pilot lamp
- 4. Positive-Reverse lever
- 5. Spindle speeds selectors
- 6. Emergency stop switch
- 7. Variable speed selectors
- 8. Slide cross feed handwheel
- 9. Toolpost clamping lever
- 10. Top slide handwheel
- 11. Saddle clamping lever

- 12. Tailstock barrel clamping lever
- 13. Tailstock clamping lever
- 14. Tailstock handwheel
- 15. Coolant pump ON/OFF button
- 16. Inching button
- 17. Threads and feeds selectors
- 18. Foot brake
- 19. Thread cutting half-nut lever
- 20. Automatic feed lever
- 21. Apron longitudinal feed handwheel
- 22. Spindle rotation (Forward and Reverse)

# INSTALLATION

#### CHUCKS AND CHUCK MOUNTING

When mounting chucks or faceplate, first, ensure that spindle and chuck tapers are scrupulously clean and that all cams lock in the correct positions, see Fig. It may be necessary when mounting a new chuck to re-set the camlock studs (A) To do this, remove the caphead locking screws (B) and set each stud so that the scribed ring (C) is flush with the rear face of the chuck-with the slot lining up with the locking screw hole (see Fig).

Now mount the chuck or faceplate on the spindle nose and tighten the three cams in turn. When fully tightened, the cam lock line on each cam should be between the two V makes on the spindle nose.

If any of the cams do not tighten fully within these limit marks, remove the chuck or faceplate and re-adjust the stud as indicated in the illustration. Fit and tighten the locking screw (B) at each stud before remounting the chuck for work.

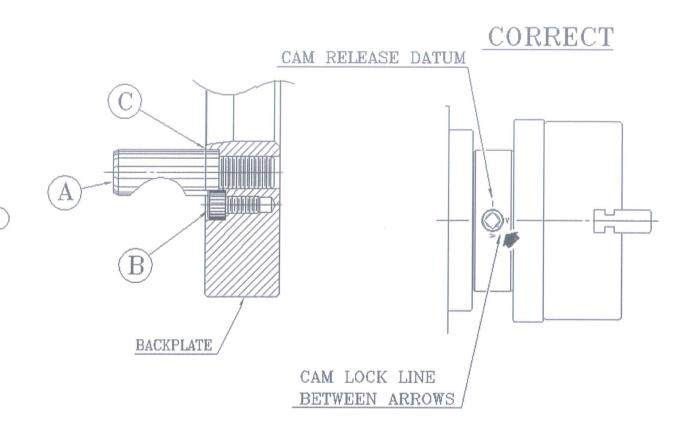
This will assist subsequent remounting.

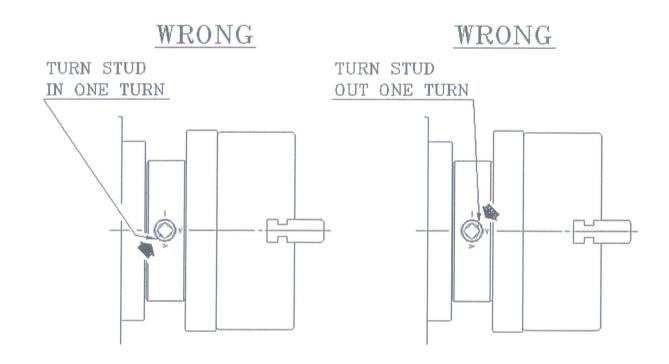
DO NOT INTERCHANGE CHUCKS OR FACEPLATES BETWEEN LATHES WITHOUT CHECKING FOR CORRECT CAM LOCKING BEFOREHAND.

IMPORTANT: Take careful note of speed limitation when using faceplate; 10 inch faceplates should not be run at speeds greater than 1000 rev/min. and 12" faceplate at not more than 770 rev/min.

# INSTALLATION

#### CHUCKS AND CHUCK MOUNTING





#### ELECTRICAL CONTROLS

The Main power switch are fitted on the front of Electrical box behind the Lathe (Head-end)

All electrical controls are fitted to the front face of the Headstock and the top of Electrical box on the top of Headstock.

(1),(2),POWER SWITCH BUTTON: when push the power switch button red color (1) on the top of headstock, the pilot lamp (3) glows and the electricity is on.
When push the power switch green color (2), the electricity is off.

(3) PILOT LAMP: When power is on, the

pilot lamp glows.

(4) EMERGENCY STOP SWITCH: press the RED mushroom—head button to stop electric power, to stop the main motor and coolant pump.

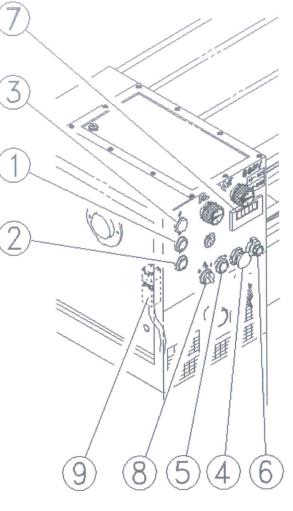
(5) INCHING: Press the GREEN button to move spindle slightly, it will make spindle speed selection very easy. (While the spindle rotation lever is set in the neutral position)

(6) VARIABLE SPEED SELECTORS: adjusting spindle speed.

(7) Spindle speed chart.

(8) Coolant pump ON/OFF swithch.

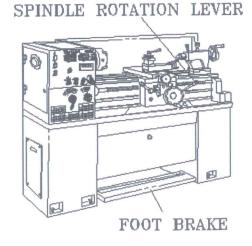
(9) End cover switch: While operator openend cover door for adjustment or main-tenance, it will stop automatically allrotation movement.



#### MAIN MOTOR CONTROLS

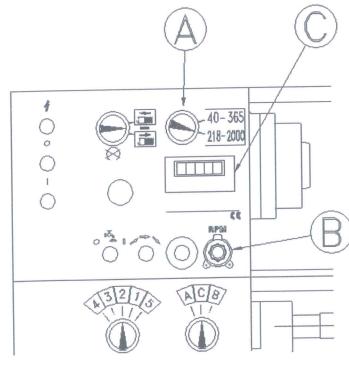
A. Main motor rdtation: Selected by the lever controls (The located on right-hand side of the Apron). Move lever out and upward to engage forward rotation of spindle, or out and down to engage reverse rotation, or returned to the central position to disengage drive.

B: Foot brake: A foot pedal between plinths operates the spindle brake.



#### SPINDLE SPEED SELECTORS

HIGH SPEED (218-2000RPM)



Main spindle can be variable controlled, from 2000 RPM to 40 RPM, divided into two groups, HIGH SPEED 2000—218 RPM, and LOWER SPEED 365—40 RPM.

Firstly, put the upper right-hand Handle(A) on the Headstock to needed speed range. ( Note: DON'T CHANGE HANDLE'S POSITION WITH SPINDLE IN MOTION. SPINDLE MUST BE MOTIONLESS WHEN CHANGE HANDLE'S POSITION ) Then, adjust Variable Speed Selectors(B) to needed spindle speed. Selectors(B) can change speed while spindle is rotating.

Spindle Speed Chart(C) equiped on the face of the Headstock shows the RPM while spindle rotating.

#### THREADS AND FEEDS

All the threads and feeds directly available from the gearbox are show on the data plate fitted on the front of the Gearbox cover, with the setting of control levers.

with the setting of control levers.

Threads and feeds direction can be changed by Positive—Reverse Knob on the headstock, and positioning control Knobs and Levers

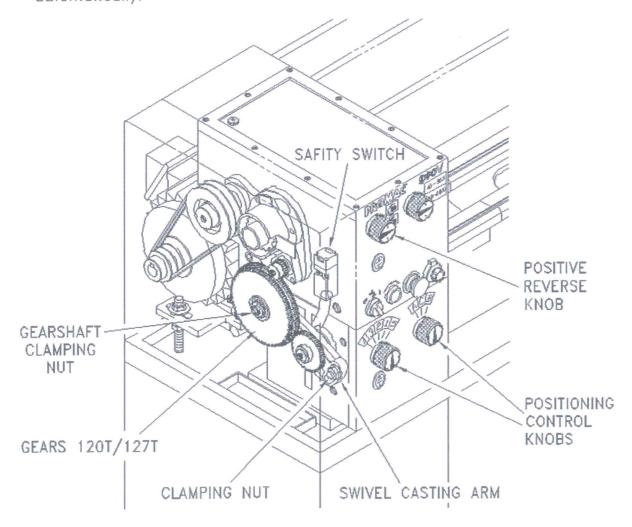
on the gearbox.

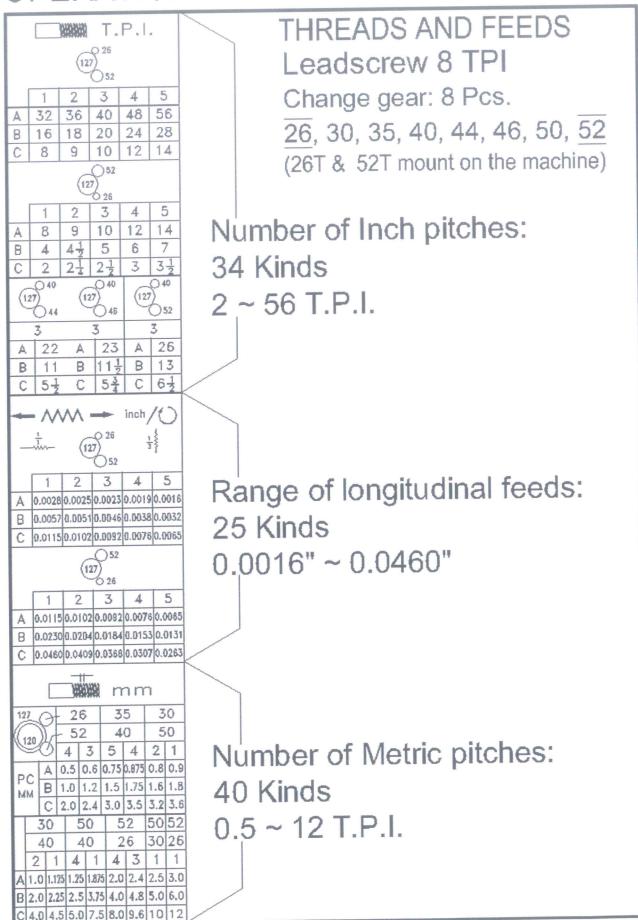
The end gear train should be arranged as in the diagrams show

on the data plate to suit threading requirements.

Loosen the clamping nut of swivel casting arm to exchange the transmission shaft gear with another gear, and to adjust clutching in screw cutting work as well as in feed work. Change of driven gear is made by loosening the 120T and 127T gears shift clamping nuts. Suitable backlash is necessary to intermediate the gear in booth cases.

P.S. Limit switch equipped in the lower—right side, while operator open End cover to permute change—gear, in order to protect operator's safty, all the machine movement will be stopped automatically.





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#### THREADING DIAL INDICATOR

A. Metric threads

The thread dial used for cutting metric screw threads on lathes equipped with metric leadscrew. To provide for the variouspitches of metric threads, several gears having different numbers of teeth are mounted on the lower end of the shaft. The vertical position of the thread dial indicator is changed as required so that the correst gear for the pitch of the thread to be cut will mesh with the leadscrew.

Each guaduation on the dial is marked with a letter which indicates the points at which the halfnuts may be engaged for certain threads. A diagram is supplied with the thread dial to show which gear and which graduations

must be used for each pitch of metric screw thread.

This dial cannot be used with an Metric leadscrew to cut Inch metric threads. For these the leadscrew nut must be kept closed and the machine reversed by use of the Changeover switch, after each cutting pass and tool with drawal.

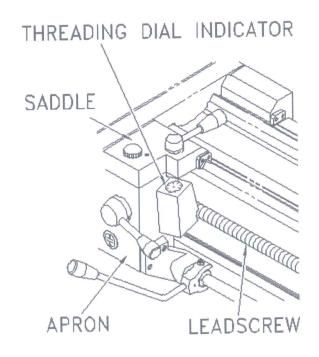
B. Whitworth threads

Located on right—hand side of the apron on lathes having an English leadscrew. Engage the indicator pinion with the leadscrew and tighten the handnut to retain indicator in engagement. To cut threads of an even number per inch, close theleadscrew nut as ANY line on the dial passes the datum mark. To cut threads of odd numbers per inch, close the leadscrew nut at any NUMBERED line.

Fractional threads of 1/2 or 1/4 t.p.i. may be cut by closing the nut at

the SAME numbered line on each pass of the tool.

or fractional threads. For these the leadscrew nut must be kept closed and the machine reversed by use of the Changeover switch, after each cutting pass and tool with drawal.









WHITWORTH THREAD DIAL					
TPI	1	TPI	1	TPI	+
4	1-8	12	1-8	38	1-8
41	7.4	13	1-4	40	1-8
44	1	14	1-8	44	1-8
5	1-4	16	1-8	48	1-8
51	2.4	18	1-8	52	1-8
6	1-8	19	1-8	56	1-8
61	13	20	1-8	64	1-8
7	1-4	22	1-8	72	1-8
8	1-8	24	1-8	76	1-8
9	1-4	26	1-8	80	1-8
91	13	28	1-8	88	1-8
10	1-8	32	1-8	96	1-8
11	1-4		1-8		1-8
LEADSCREW PITCH 8T.P.I.					

#### APRON CONTROLS

In addition to handwheel traverse, the carriage can be power—operated through controls on the front of the apron.

Automatic feed lever (A) if move upwards, carriage would do manual operation. If move lever (A) downwards, it would do cross—feed operation.

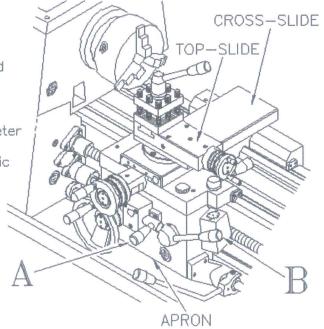
Lever (B) is pressed downward to engage the leadscrew nut for screwcutting. To avoid undue wear. Release the nut except when screwcutting.

#### CROSS SLIDE AND TOP SLIDE

A solid topslide is fitted as standard to the cross—slide, carried on a rotatable base the cross—slide is marked 45—0—45 deg. For accurate indexing.

Handwheel dials are graduated in inch or metric divisions to suit the operating screw and fitted.

The cross—slide can be power operated by pulled downward the feed per spindle revolution, or if can be hand—operated using the large—diameter dial graduated in either inch or metric divisions to suit the operating screw and nut fitted.

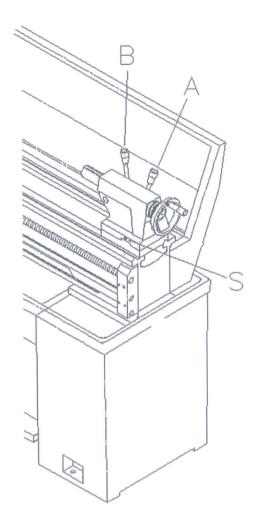


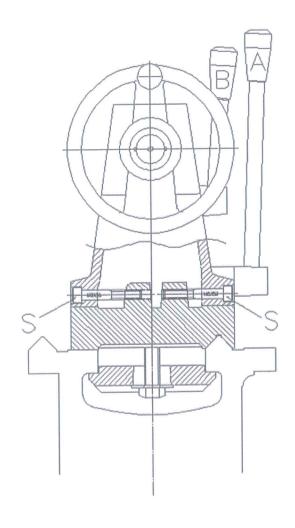
#### TAIL STOCK

Can be free movement along the bed by unlacking the clamp lever (A).

The tailstock barrel is locked by lever (B).

The tailstock can be set—over for production of shallow tapers or for re—alignment. Release the clamping lever and adjust screws (S) at each side of the base to move tailstock laterally across the base. An indication of the setover is given by the datum mark (C) at the tailstock end face, as shown in Fig 18. Apply clamp lever after adjustment of set—over.





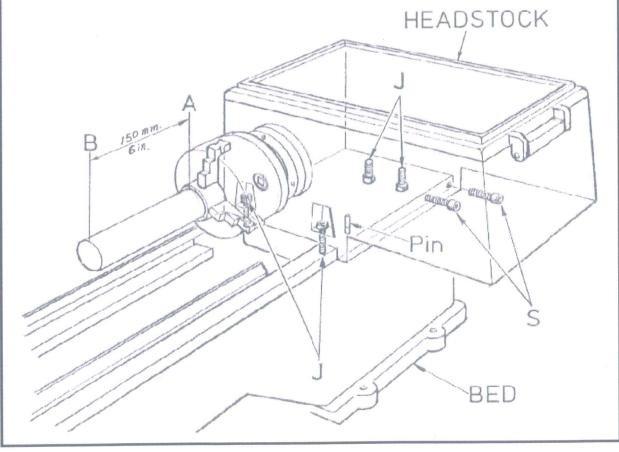
# LATHE ALIGNMENT ( Part.1 )

With the lathe installed and running. We recommed a check on machine alignment before commencing work. Check levelling and machine alignment at regular periods to ensure continued lathe accuracy.

#### A. Headstock check

Take a light cut with a keen tool over a 6 in (150mm.) length of 2 in. dia. (50mm.) steel bar gripped in the chuck but not supported at the feed end. Micrometer readings at each end of the turbed length (at A and B) should be the same.

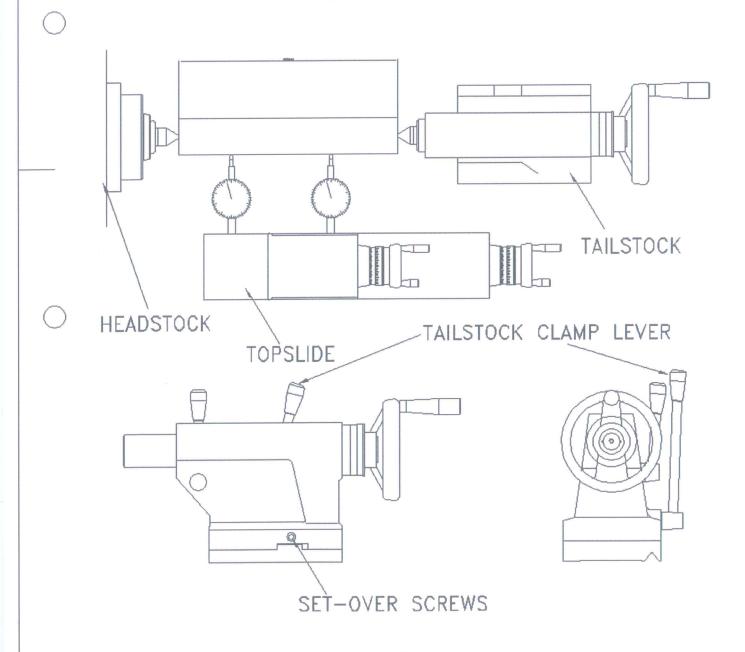
To correct a difference in readings, slacken the four headstock hold—down screws (S) and adjust the set—over pad (P) beneath the headstock, to pivot the headstock about the dowel (D). Tighten all screws, after adjustment and repeat the test—cut / micrometer—reading, sequence until micrometer readings are indentical, so machine now cutting absolutely parallel.



# LATHE ALIGNMENT (part2)

Tailstock check: Using a 12 in. (305mm.) ground steel bar fitted between centers of headstock and tailstock. Check the alignment by fitting a dial—test indicator to the topslide and traversing the center line of the bar.

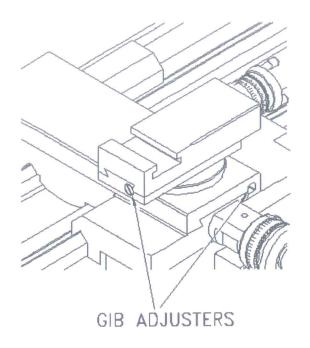
To correst error, release the tailstock clamp lever and adjust the two set—over screws provided. Continuously check and correct until the alignment is perfect.



#### SLIDE WAYS ATTENTION

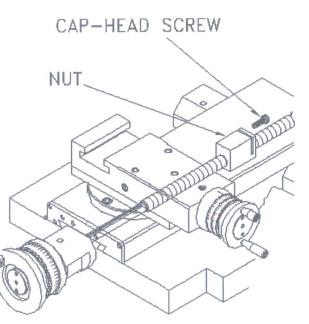
Tapered gib strips are fitted to slideways of saddle cross—slide and top (compound) slides so that any slackness which may develop can be rectified.

Ensure that slideways are thouaughly cleaned and lubricated before attempting adjustment. Then reset the gibs by slacken—ing the rear gib screw and tigh—tening the front screw. Check constantly for smooth action throughout full slide travel. Avoid over—adjustment which can result in increased wear—rate and stiff or jerky action.



#### CROSS-SLIDE NUT

This is adjustable for elimi—
nation of slackness which may
develop in service. Reduce back—
lash by the cap—head screw in the
rear of the nut. Then make only
small adjustment by the cap—head
screw. Before operating the
cross—slide, check several times
by hand to be sure of smooth
operation throughout travel.

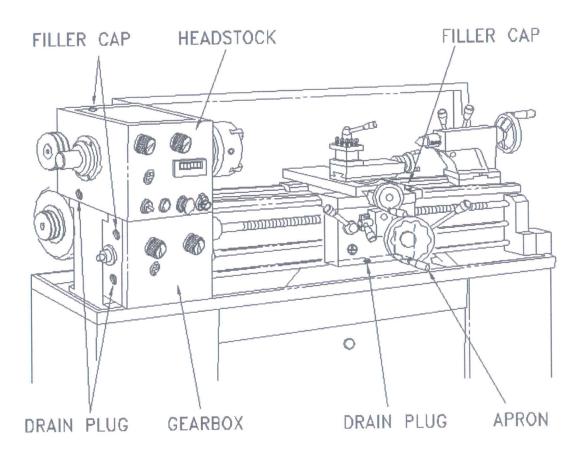


# LUBRICATION ( Part.1 )

Headstock bearing and gears are splash lubricated. Ensure that oil lever is kept between H-L lever mark on the sight glass in the front of headstock. After long time of operation, when the headstock lubrication oil becomes unclean, it should be drained out to refill fresh lubrication oil.

To change oil in headstock, set apron control lever to central position and stop the main motor. Unscrew the drain plug beside headstock, then the oil tank can be easily drained out for changing oil. A filler plug is fitted beside the left end of headstock accessible after removal of the end guard.

The gearbox and apron are splash-lubricated form an internal reservoir of oil. Check the oil level constantly to the mark on the oil sight window at the right side face of the gear box; a weekly check is recommended, with the oil changed every year. Fill oil through a filler cap in the top of the gearbox, enclosed by the end—guard. Drain from a drain plug in the bottom of the gearbox. The apron can be drained by unscrewing a hex—headed drain plug in the bottom.



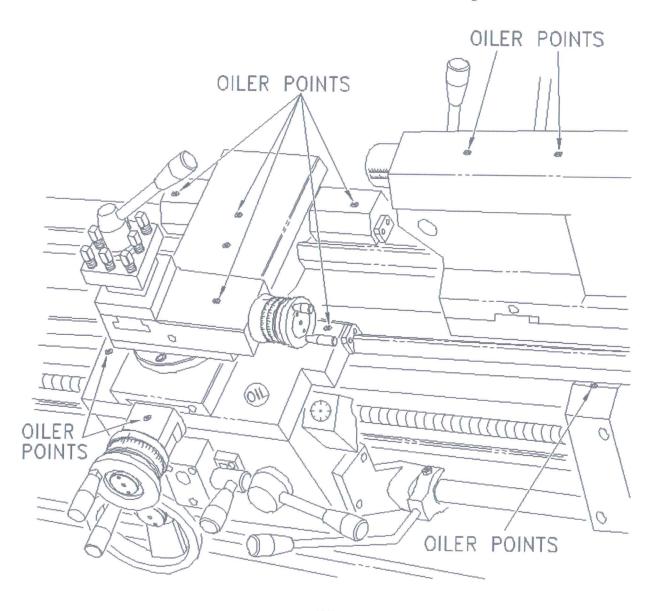
# LUBRICATION ( Part.2 )

In addition, oil gun is provided to oil the oiler points on the saddle, cross—slide, cross—slide nut and top—slide with light machine oil or way lubricant, see Fig.

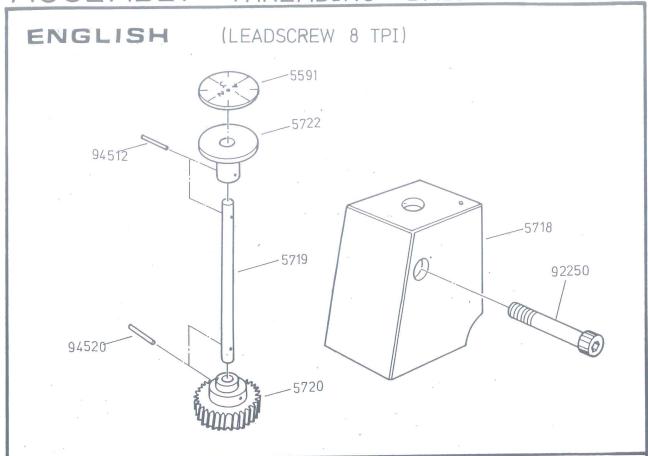
Oiler points, on the top of tailstock and on the bracket for leadscrew & feed road, must to be poured into oil every day by using oil gun.

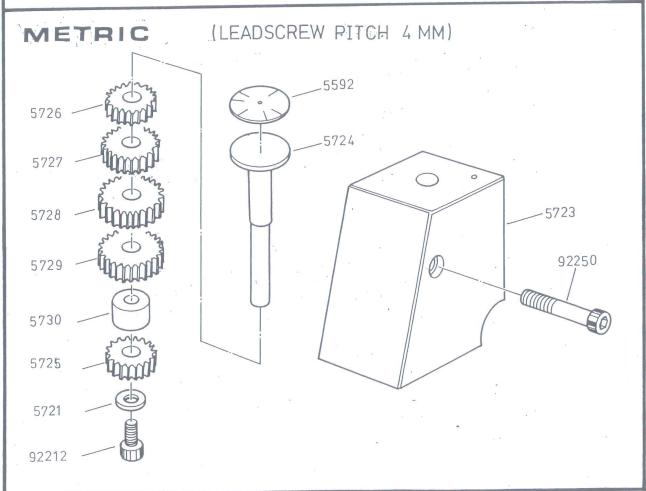
It is recommended that all slideways, leadscrew and feed shaft are cleaned off ( a bristle paint brush is useful for this ) and lightly oiled after each period of work.

NOTE: Using incorrect grade of oil can cause damage.

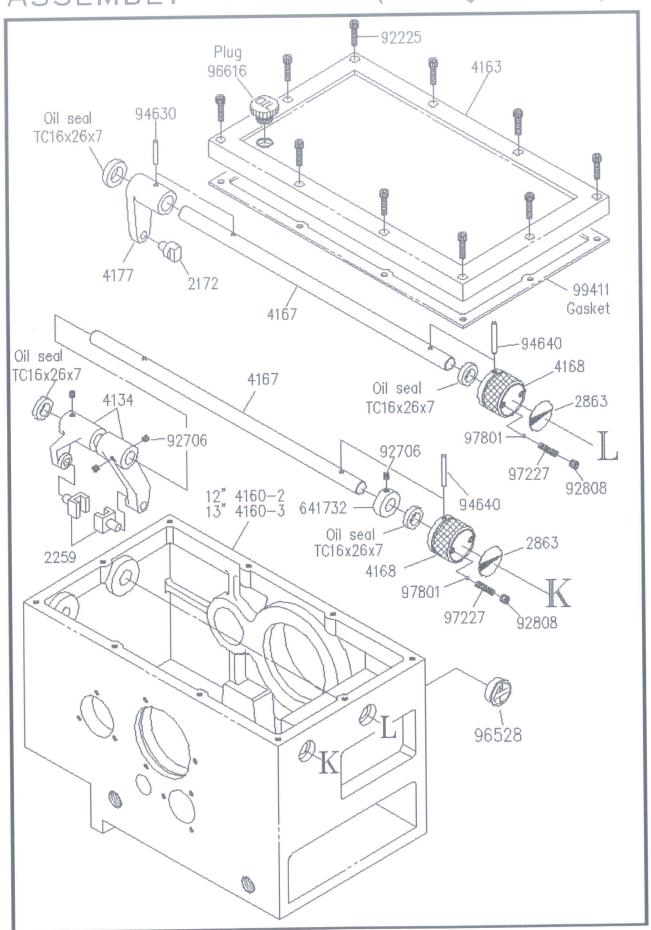


# ASSEMBLY THREADING DAILS

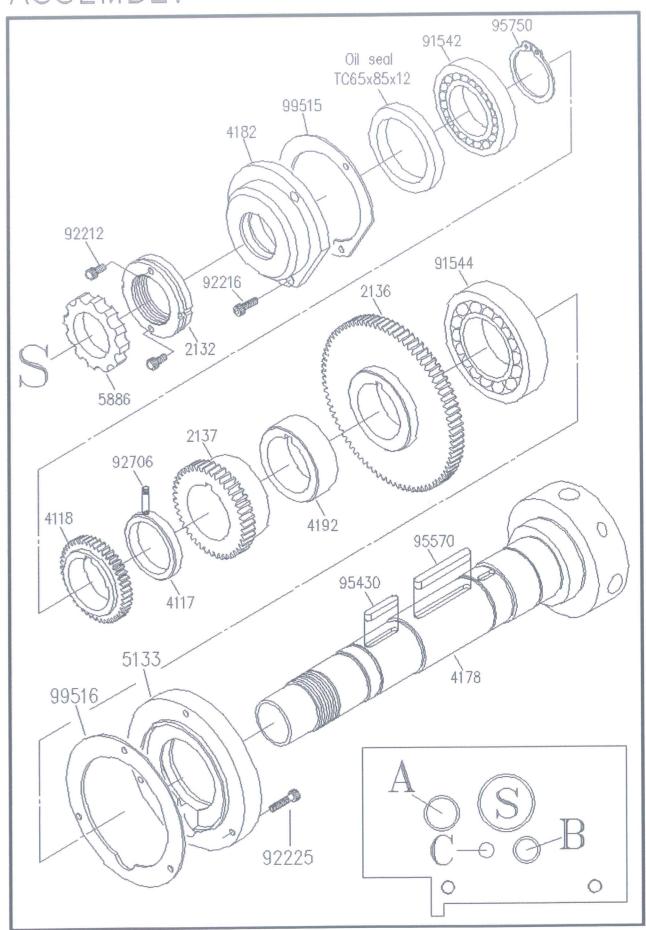




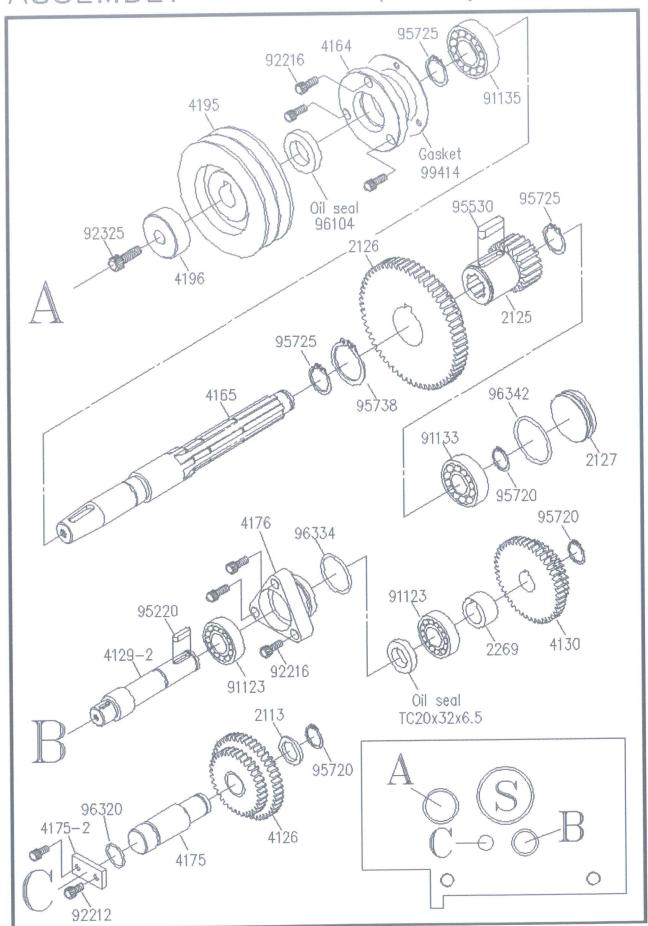
# ASSEMBLY Headstock (Casting & Lever)

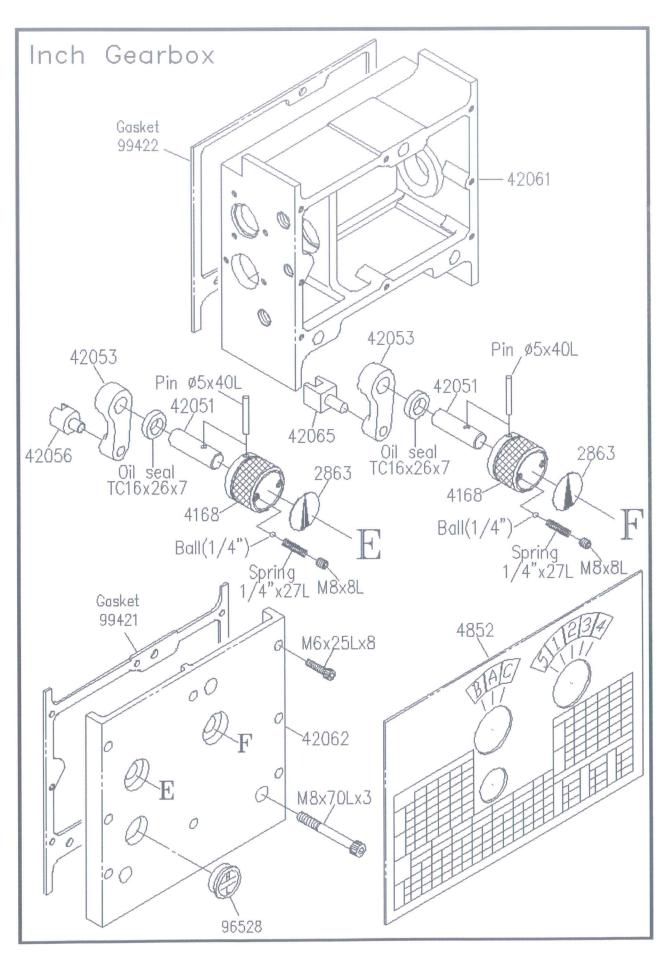


# ASSEMBLY Headstock

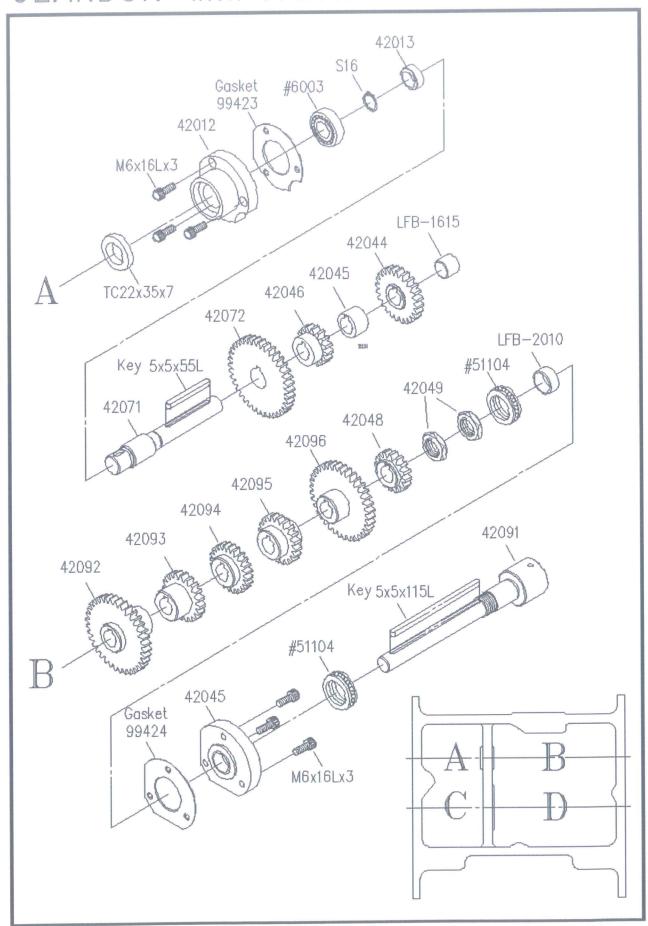


# ASSEMBLY Headstock (Casting & Lever)

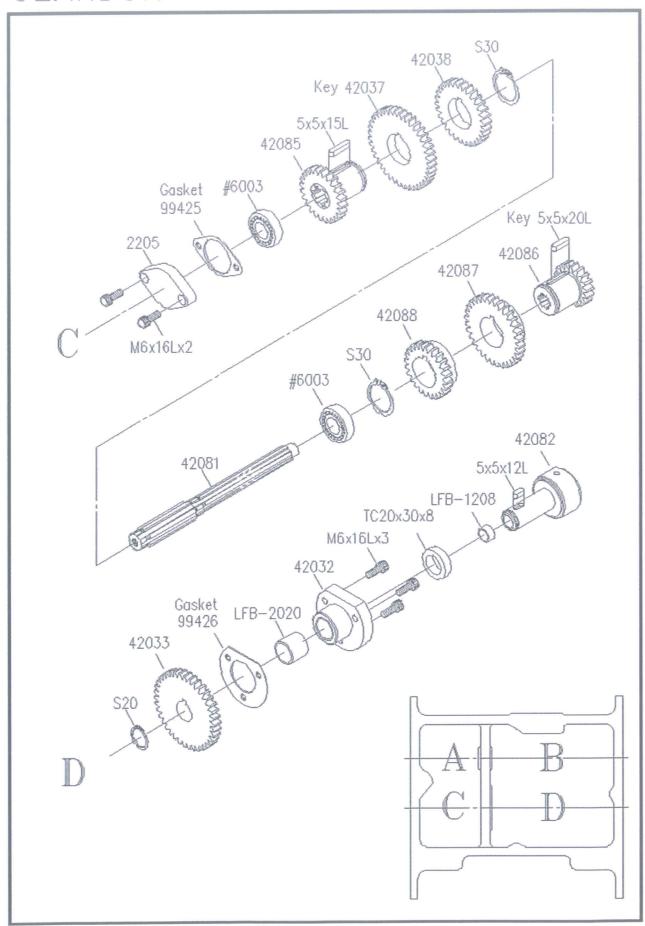




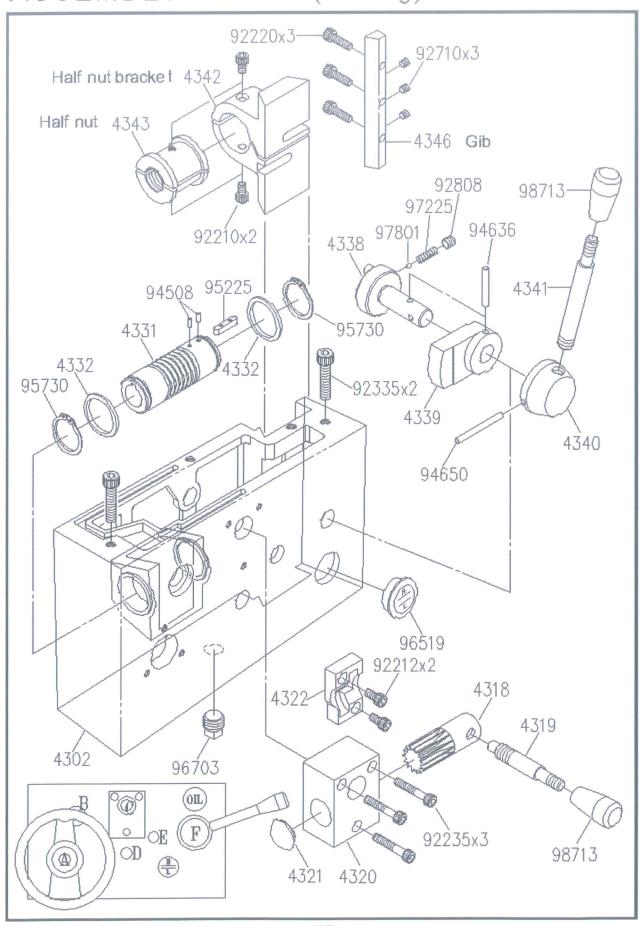
# GEARBOX Inch Gearbox



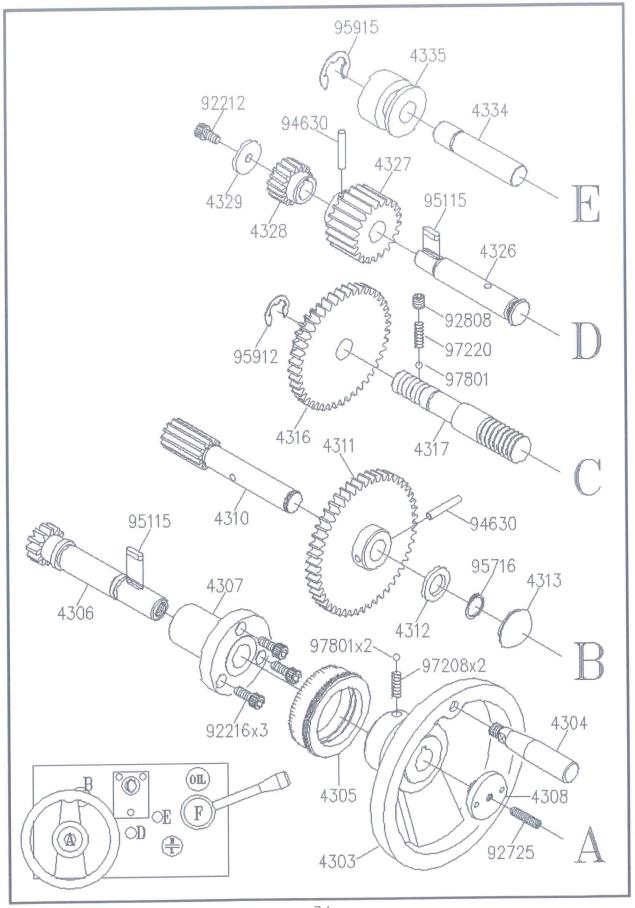
# GEARBOX Inch Gearbox

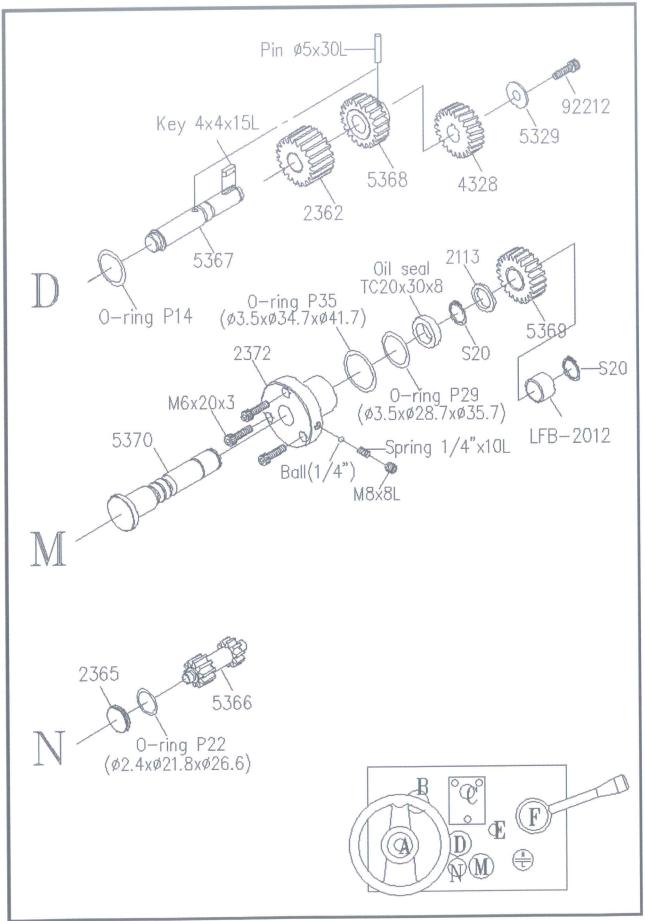


# ASSEMBLY APRON (Casting)

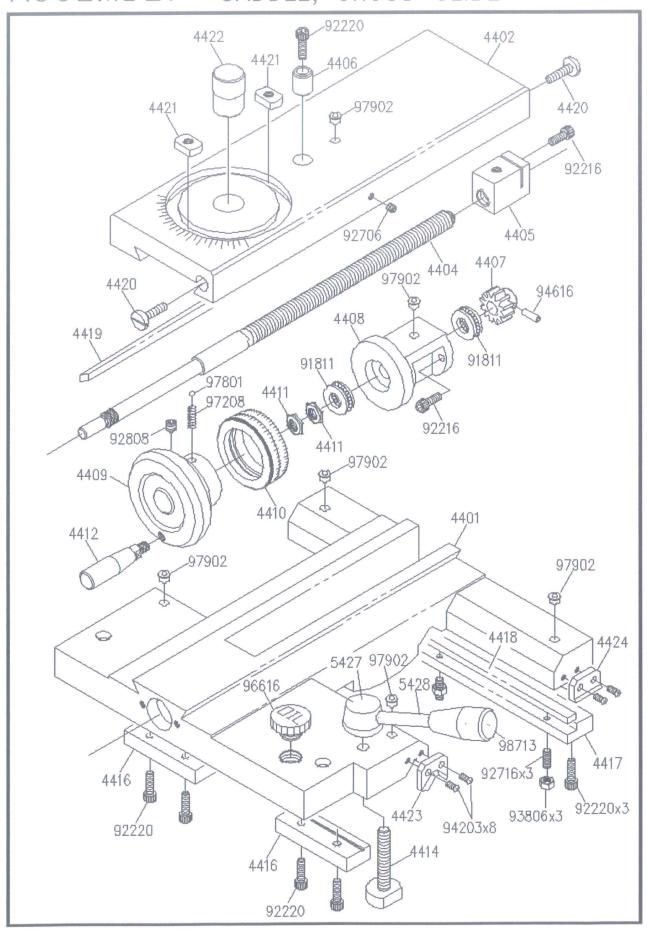


# ASSEMBLY APRON (Gears &Shaft)

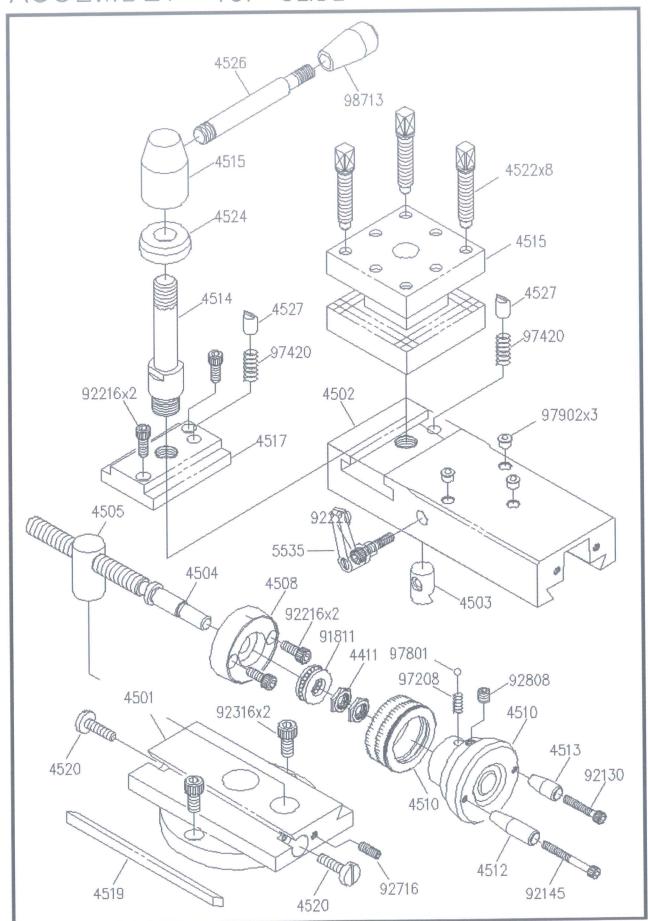




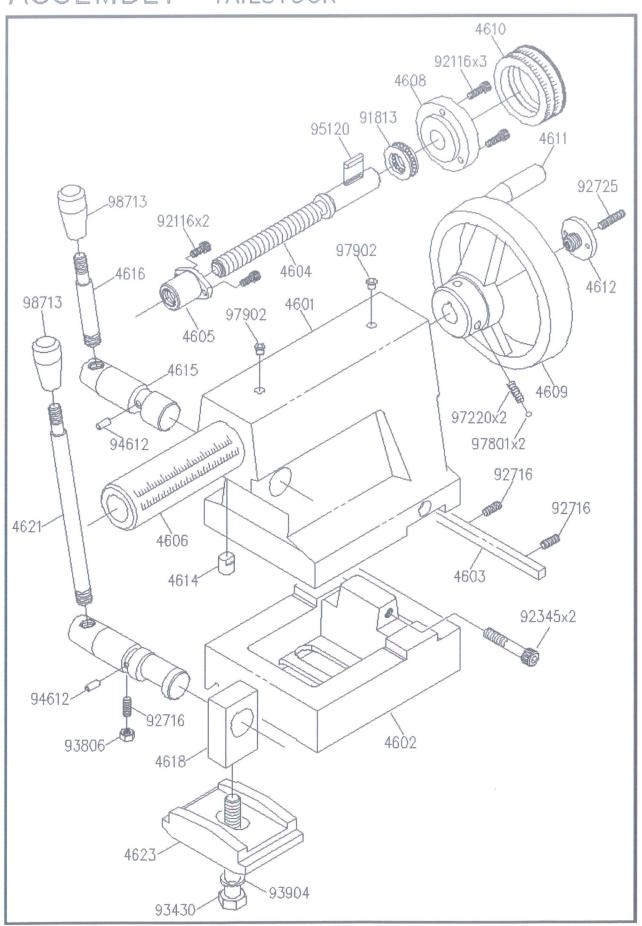
# ASSEMBLY SADDLE, CROSS-SLIDE

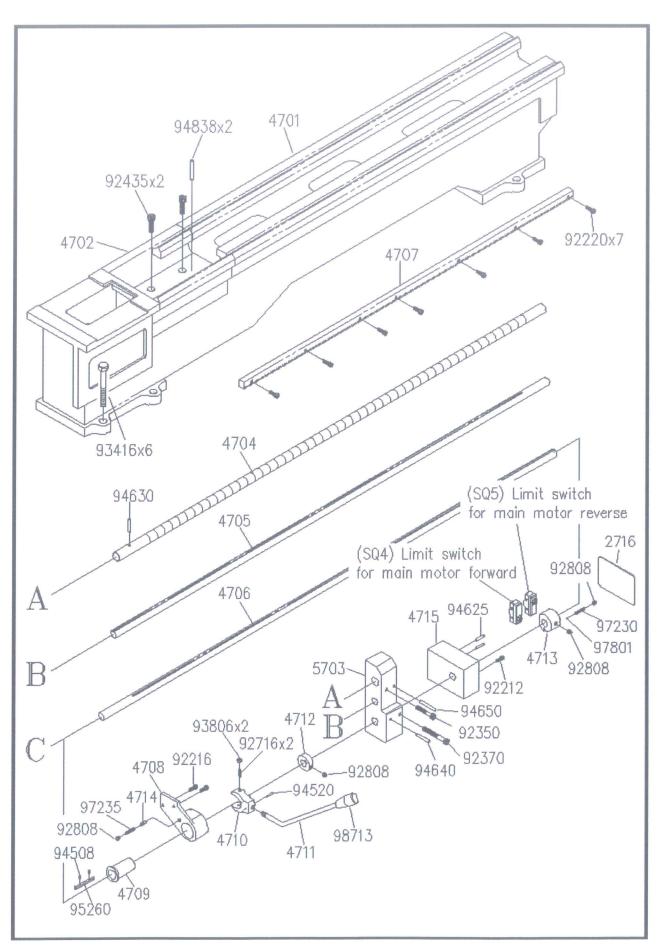


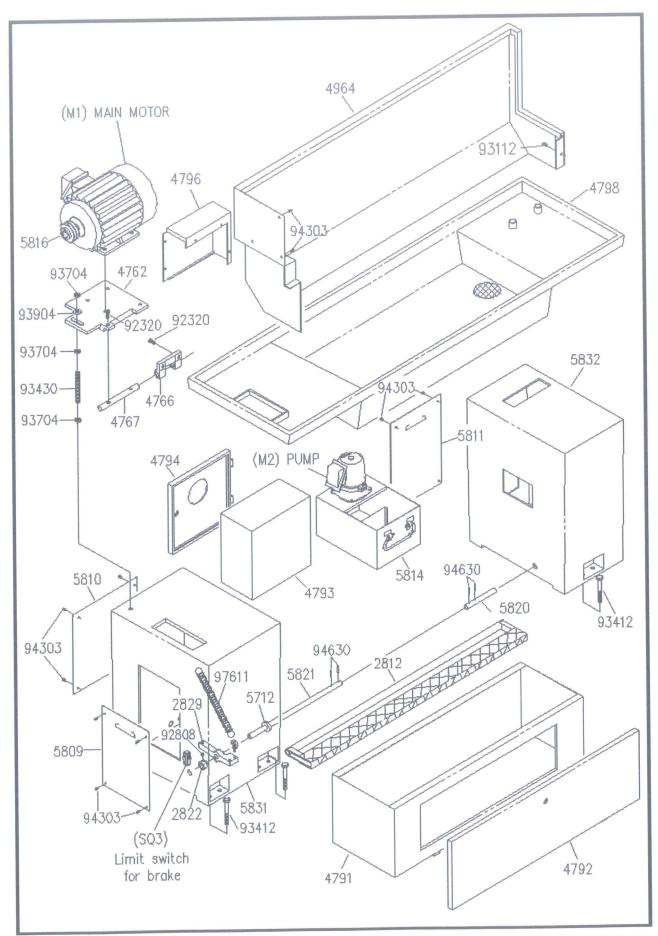
# ASSEMBLY TOP-SLIDE



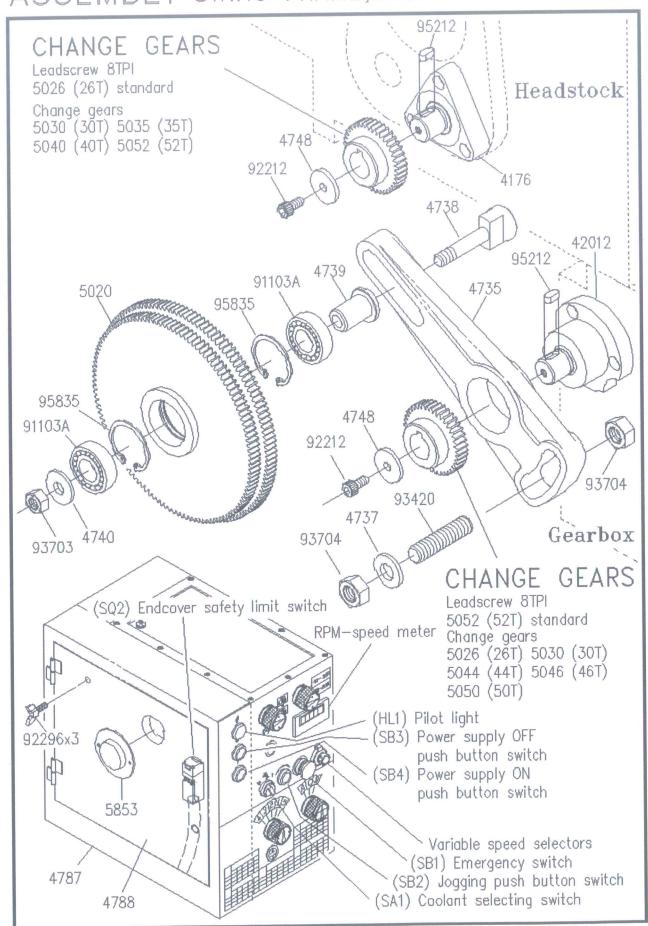
# ASSEMBLY TAILSTOCK



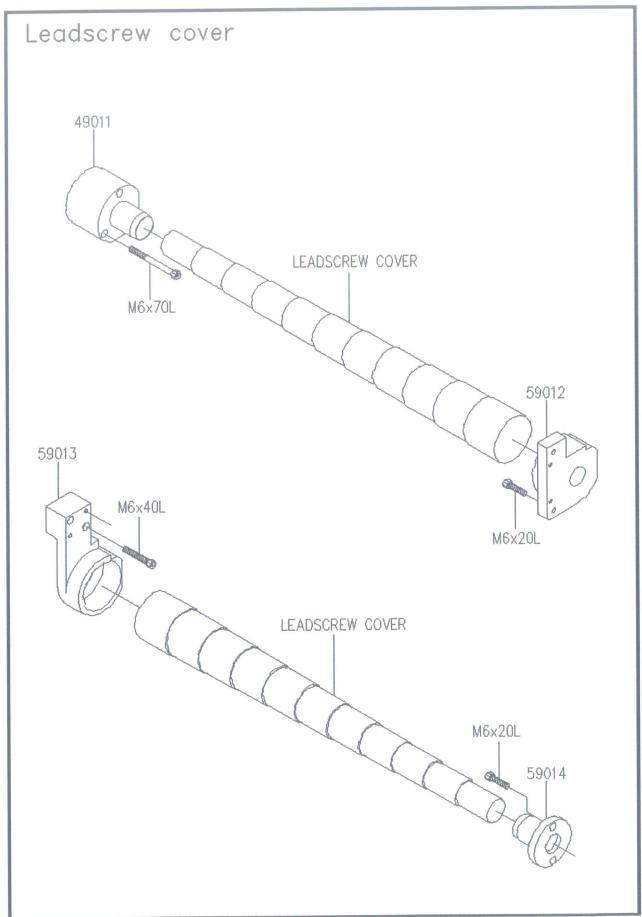




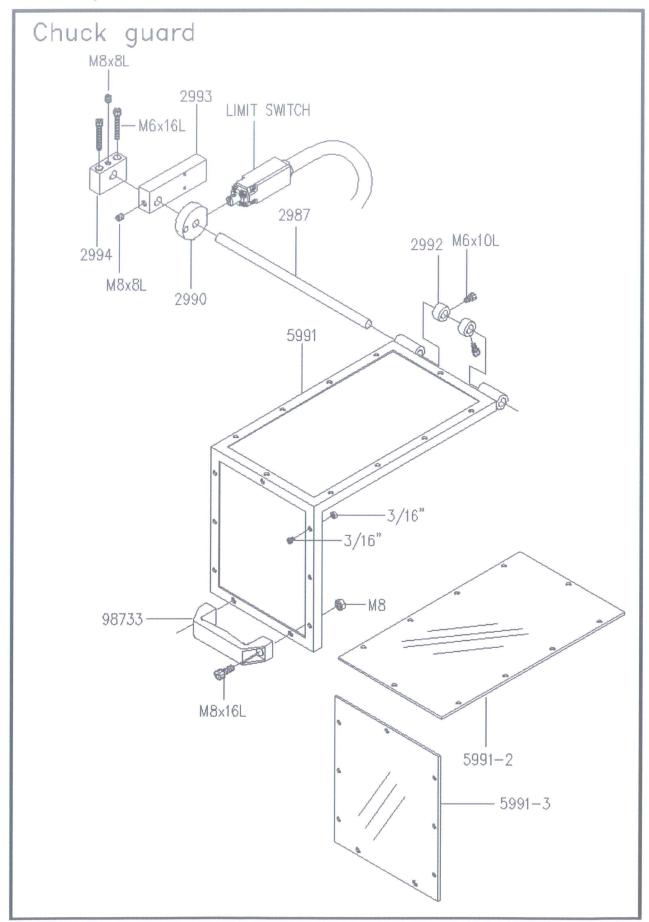
# ASSEMBLY SWING FRAME, END GEARS & COVER



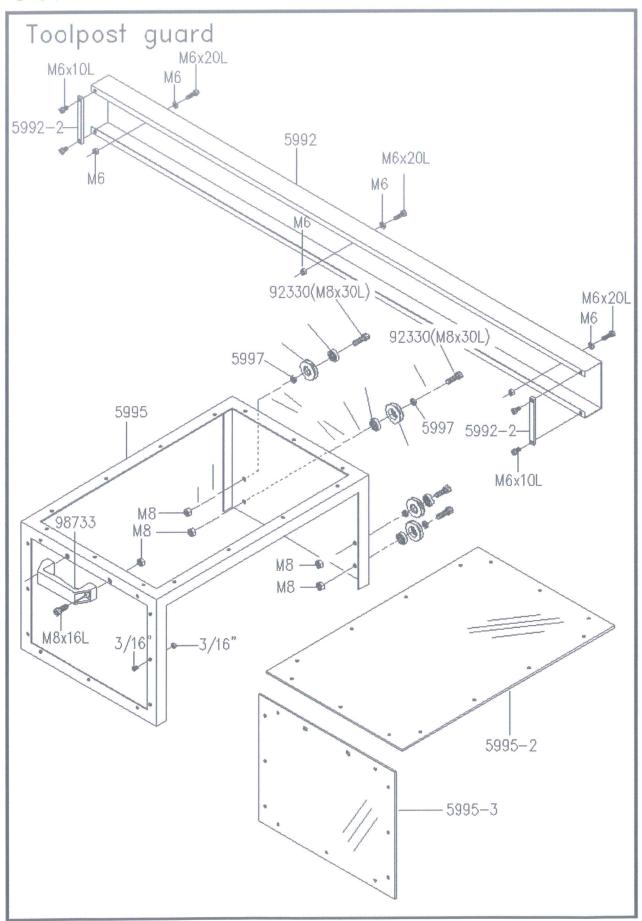
# GUARD



# GUARD



# GUARD



Headst	ock	Gearbox (Inch)			
Part No.	Description Q'ty	Part No.	Description	Q'ty	
4110 4117 4118	Cover 1 Collar 1 Gear 1.75M 45T 1	42061 42062	Gearbox casting Cover	1	
4119 4124 4126 4129 4130 4131 4134 4135	Collar 1 Collar 1 Gear 1.75M 35/45T 1 Shaft 1 Gear 1.75M 35/45T 1 Collar 1 Lever 1 Shift fork 1	42012 42013 42022 42032 42033 42037 42038 42042	Gear 2M 401 Gear 2M 30T Cover	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	
2127 2132 2136 2137 2172	Index ring 1 Collar 1 Headstock casting 1 Cover 1	42046 42048 42049 42051 42052	Gear 2M 16T Nut Lever Handle Shift lever Shift fork Shift fork	1 1 1 2 2 2 2 1 1	
4165 4166 4167 4168 4173 4175	Shaft 1 Shaft 1 Shaft 1 Handle 2 Main Spindle 1 Shaft 1	42081 42082 42085 42086 42087 42088	Shaft Shaft Gear 2M 20T Gear 2.25M 20T Gear 2.75M 20T Gear 2M 25T	1 1 1 1 1	
4195 4196 4197	Cover 1 Shift fork 1 Collar 1 Pulley 1 Washer 1 Pulley 1 Pulley 1	42093 42094 42095	Shaft Gear 2M 30T Gear 2.75M 20T Gear 2.75M 18T Gear 2.75M 16T Gear 2.25M 28T	1 1 1 1 1	

Apron		
Part No.	Description	Q'ty
5311 5312 5313 5316 5317 5318 5319 5320 5321 5322 5323 5324 5326 5327 5328 5329 5331	Apron Handwheel Handle Index ring Shaft 2M 12T Keep assy Plug Shaft 2M 12T Rack pinion 1.5M 13T Gear 2M 50T Collar Plug Gear 2M 44/22T Shaft Gear shaft 1.5M 14T Lever Keep assy Plug Cam Gear shaft 1.5M 14T Lever Shaft Gear 2M 22T Worm gear 1.5M 18T Washer Worm Collar Shaft Collar Shaft Lever Halfnut bracket Halfnut Gib Rack pinion 1.5M 13T Worm gear 1.5M 18T Half nut Apron Shaft Shaft Shaft	

Sadd		
Part No	Description	Q'ty
4401	Saddle entire	4
4402	Saddle casting	1
4404	Crossslide cover	1
4405	Screw Nut	1
4406	Collar	1
4407	Gear 2M 12T	1
4408	Keep assy.	1
4409	Handwheel	4
4410	Index ring	1
4411	Nut	1 1 1 1 1 1 1 4
4412	Handle	1
4414	Set screw	1
4415	Washer	1
4416	Strip	2
4417	Strip	1
4418	Gib	1
4419	GIb	1 1 2 1 1 1
4420	Gib screw	2 1 2 2 1
4421	Nut	2
4422	Pirot	1
4423	Wipper	2
4424	Wipper	2
5427	Handle	1
5428	Lever	1
Comp	ound rest	
Part No.		n*i
ruii No.	Description	Q'ty
4501	Swivere slide	1
4502	Top slide	1
4503	Pad	1
4504	Screw	1 1
4505	Nut	1
4506	Nut	1
4508	Keep assy.	1
4509	Handwheel	1
4510	Index ring	1
4512	Handle	1
4513	Handle	1
4514 4515	Bolt	1
4515	Toolpost	1
4519	Nut Glb	1
4520	Gib screw	2
4522	Screw	1 1 1 1 1 2 8 1
4524	Washer	1
4525	ScrewHandle	1
4526	Lever	1
4527	Pad	1

Tailsto	ck	
Part No.	Description	Q'ty
4601 4602 4603 4604 4605 4606 4608 4609 4610 4611 4612 4614 4615 4616 4618 4620 4621 4623	Tailstock casting Base Gib Screw Nut Barrel Keep assy. Handwheel Index ring Handle Screw Pad shaft Handle Pirot block Shaft Handle Clamp plate	
	Floor stand	
Part No 2812	Description  Brake pad	Q'ty  1
4189 4701 4702	Guard Bed casting Gap piece	weerly seemly seemly
4704 4705 4706	Leadscrew Feed shaft Third—rod shaft	1 1 1 1
4707 4708	Rack Bracket	
4709 4710 4711	Sleeve Fork Lever	1
4712 4713 4714	Collar Collar Pîn	1 1
4715 4716 4721	Box over Washer	1 1 3
4723 4724	Guard Shaft	
4725 4726 4727	Gear 1.25M 20T Gear 1.25M 21T Gear 1.25M 22T	1
4728 4729	Gear 1.25M 26T Gear 1.25M 27T	and disease

	Floor stand	
Part No.	Description	Q'ty
4735 4737 4738 4739 4740 4748 4762 4766 4767 4783 4787 4788 4791 4792 4793 4794 4795 4796 4797 4798 4962 4991 5716 5809 5810 5811 5831 5832 5991 5995 5759	Shaft collar Washer Washer Motor platform Bracket Shaft Guard End cover End cover Cabinet Front cover Electric box Cover Plate Guard Guard Chip pan Splash guard Chuck guard Cover Cover Cover Cover Cover Cover Cover Cover Colant tank Floor stand Floor stand Chuck guard Toolpost guard Safty Pin	1 1 2 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
Change Part No.	Description	Q'ty
ANNAL DESIGN SERVICE SERVICE ASSESSED.	AND DESCRIPTION OF PERSONS AND AND ADDRESS	1
5026 5030 5035 5040 5046 5050	Gear 1.25M 26T Gear 1.25M 30T Gear 1.25M 35T Gear 1.25M 40T Gear 1.25M 46T Gear 1.25M 50T Gear 1.25M 52T	work such work soul

## GUARD FOR "CE" STANDARD

#### Leadscrew cover

Part No.	Description
delica delica ideali delica ideali	come come come come come come come come
49011	Support
59012	Bracket
59013	Bracket
59014	Support
92220	Socket head cap screw M6x20mm
92240	Socket head cap screw M6x40mm
92270	Socket head cap screw M6x70mm
Chuck	guard

Part No.	Description
2987 2992 2993 2994	Support rod Collar Bracket Support
5991 5991-2 5991-3 92210 92316	Chuck guard shield Chuck guard shield Chuck guard shield Socket head cap screw M6x10mm Socket head cap screw M8x16mm
92808 93700 93808 94203	Set screw M8x8mm. Nut 3/16" Nut M8 Screw 3/16"x3/8"

### Toolpost guard

98751 Handle

5992 Guide rod 5992—2 Guide plate	Part No.
5995 Toolpost guard 5995—2 Toolpost guard 5995—3 Toolpost guard 5988 Roller 5997 Collar 91112 Bearing #608 92210 Socket head cap screw M6x10m 92220 Socket head cap screw M6x20m 92316 Socket head cap screw M8x16m 92325 Socket head cap screw M8x16m 92325 Socket head cap screw M8x25m 93700 Nut 3/16" 93806 Nut M6 93808 Nut M8 94203 Screw 3/16"x3/8" 98751 Handle	5992-2 5995 5995-2 5995-3 5988 5997 91112 92210 92210 92316 92325 93700 93806 93808 94203

#### Gasket

#### Part No. Description

99411	Gasket	for	Headstock cover 4163
99412	Gasket	for	4162
99413	Gasket	for	4110
99414	Gasket	for	4164
99421	Gasket	for	Gearbox cover 42002
99422	Gasket	for	Gearbox 42001
99424	Gasket	for	42045
99425	Gasket	for	2205
99426	Gasket	for	42032
99471	Gasket	for	4715

Part	No.	Desc	ripti	on	
04044	D 1 -			e tanan jumba assaur to	BRAD ANDSAUT
91011	Bearin				
91121	Bearin	W.	003	w.	
91122			0032	_	
91123			004		
91125					
91131					
91133					
	Bearin				
	Bearin				
	Bearin			-	
	Thrust				
91813					
91814					
91815					
91816		No.51			
91823		No.51			
91824		No.51			
91841	Thrust	No.29			
91842		No.29			
91843		No.29			
91844	Thrust	No.29	04		
92116	Socket	head	cap	screw	M5x16mm
92130	Socket	head	cap		M5x30mm
92145	Socket	head	cap	screw	M5x45mm
92210	Socket	head	cap	screw	M6x10mm
92212	Socket	head	cap		M6x12mm
92216	Socket	head		screw	M6x16mm
92220	Socket	head		SCIEW	M6x20mm
92225	Socket	head		screw	M6x25mm
92230	Socket	head		screw	M6x30mm
92235	Socket	head	cap		M6x35mm
92240	Socket		cap		M6x40mm
92245	Socket			screw	
92250	Socket			screw	
92255				screw	
92296	Butterf				
92312	Socket	head	cap	screw	M8x12mm
92316	Socket			SCIEW	M8x16mm
92320	Socket			screw	M8x20mm
92325	Socket			SCIEW	M8x25mm
92330	Socket			screw	M8x30mm
92335	Socket			screw	M8x35mm
92340	Socket			screw	M8x40mm
92345	Socket			screw	M8x45mm
92350	Socket			screw	M8x50mm
92370	Socket	head	cap		M8x70mm
45410	JUVIOI	HOUN	vah	JUIUN	MOAT VIIIII

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Part No.
           Description
92425 Socket head cap screw M10x25m
92430 Socket head cap screw M10x30m
92435 Socket head cap screw M10x35m
92440 Socket head cap screw M10x40m
92445 Socket head cap screw M10x45m
92525 Socket head cap screw M12x25m
92535 Socket head cap screw M12x35m
92540 Socket head cap screw M12x40m
92706 Set screw M6x6mm.
92708 Set screw M6x8mm.
92710 Set screw M6x10mm.
92712 Set screw M6x12mm.
92716 Set screw M6x16mm.
92720 Set screw M6x20mm.
92725 Set screw M6x25mm.
92808 Set screw M8x8mm.
92814 Set screw M8x14mm.
92012 Set screw M12x12mm.
93112 Cap screw 1/41-1/4 in.
93314 Cap screw 3/8x1-1/2 in.
93320 Cap screw 3/8x2 in.
93324 Cap screw 3/8x2-1/2 in.
93330 Cap screw 3/8x3 in.
93406 Cap screw 1/2x3/4 in.
93412 Cap screw 1/2x1-1/4 in.
93414 Cap screw 1/2x1-1/2 in.
93416 Cap screw 1/2x1-3/4 in.
93420 Cap screw 1/2x2 in.
93424 Cap screw 1/2x2-1/2 in.
93430 Cap screw 1/2x3 in.
93700 Nut 3/16 in.
93701 Nut 1/4 in.
93703 Nut 3/8 in.
93704 Nut 1/2 in.
93806 Nut 6 mm.
93808 Nut 8 mm.
93903 Washer 3/8 in.
93904 Washer 1/2 in.
93906 Washer 3/4 in.
93912 Washer 6 mm.
93942 Spring washer 6 mm.
93913 Washer 8 mm.
93943 Spring washer 8 mm.
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Part No. Description
94102 Screw 1/8x1/4 in. 94103 Screw 1/8x3/8 in.
94202 Screw 3/16x1/4 in. 94203 Screw 3/16x3/8 in. 94303 Screw 1/4x3/8 in. 94308 Screw 5/32x3/16 in. 94403 Nail 2 mm. 94409 Screw 1/4x1 mm. 94508 Pin 3x8 mm. 94512 Pin 3x12 mm. 94520 Pin 3x20 mm. 94524 Pin 3x24 mm.
94612 Pin 5x12mm. 94616 Pin 5x16mm. 94620 Pin 5x20mm. 94625 Pin 5x25mm. 94630 Pin 5x30mm. 94634 Pin 5x34mm. 94635 Pin 5x35mm. 94636 Pin 5x36mm. 94640 Pin 5x40mm. 94645 Pin 5x45mm. 94660 Pin 5x50mm.
94830 Taper pin 4x30mm. 94838 Taper pin 4x38mm.
95110 Key 4x10mm. 95115 Key 4x15mm. 95120 Key 4x20mm. 95140 Key 4x40mm.
95210 Key 5x10mm. 95212 Key 5x12mm. 95215 Key 5x15mm. 95220 Key 5x20mm. 95225 Key 5x25mm. 95230 Key 5x30mm. 95235 Key 5x35mm. 95240 Key 5x44mm. 95244 Key 5x44mm. 95245 Key 5x45mm. 95250 Key 5x50mm. 95260 Key 5x60mm. 95270 Key 5x70mm.

Part No	).	Desci	ripti	on	
	Key Key Key Key Key	6x15i 6x25i 6x75i	mm mm		
95440 95450	Key Key Key Key	7×40 7×50	mm mm		
95540 95550	Key Key Key	8×30 8×40 8×50 8×60	mm mm mm	l.	
95712 95715 95716 95718 95720 95725 95730 95738 95740 95750 95755	Circli Circli Circli Circli Circli Circli Circli Circli Circli Circli	ip S-	-15 -16 -18 -20 -25 -30 -38 -40 -50	mm. mm. mm. mm. mm. mm. mm. mm. mm.	
95835 95847	Circl			mm.	
95906 95912 95915 95919	Circl Circl Circl	ip E-	-15	mm. mm. mm.	
96103 96104			TC TC	25×4 25×4	

Part N	o. Description
96309 96311 96314 96316 96320 96324 96325 96334 96343 96343	O-ring 25x31x3.0mm. O-ring 34x40x3.0mm. O-ring 38x45x3.5mm. O-ring 43x51x4.0mm. O-ring 44x50x3.0mm. O-ring 58x64x3.0mm.
96519 96528	Oil sight 3/4 in.(19mm.) Oil sight 1-1/8 in.(28mm.)
96603 96616 96703 96704	Plug 3/8 G.P. Plug 3/4 in.(P.V.C.) Plug 3/8 G.P. Plug 1/2 G.P.
96803	Elbow 3/8 G.P.
97115	Spring 3/16 in.x 15mm.
97210 97220 97225	Spring 1/4 in.x 8mm. Spring 1/4 in.x 10mm. Spring 1/4 in.x 20mm. Spring 1/4 in.x 25mm. Spring 1/4 in.x 30mm. Spring 1/4 in.x 35mm. Spring 1/4 in.x 50mm.
97420 97430 97435 97440 97460	Spring 3/8 in.x 20mm. Spring 3/8 in.x 30mm. Spring 3/8 in.x 35mm. Spring 3/8 in.x 40mm. Spring 3/8 in.x 60mm.
97611 97621	Spring Spring
97801 97803	Ball steel 1/4 in.dia. Ball steel 3/8 in.dia.

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Part No. Description
97901 Oller 1/4 in.
97902 Oller 5/16 in.
98128 Belts Vee A-28 in.
98713 Handle 3/8 in.(black)
98723 Handle 3/8 in.(red)
98733 Handle (black)
98902 Brake shoes assy.
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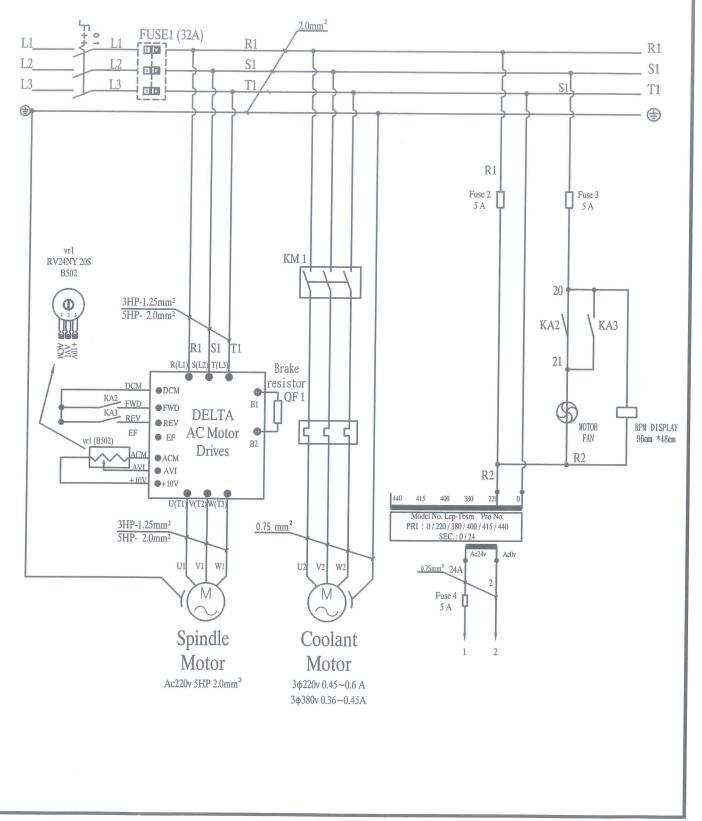
	00	UEDIUE OF	FLECTRIC	A L A		MENIT	
_		HEDULE OF					
Item designation	Circuit	Description and function	Technical data	Quantity	Supplier	Suppliers reference	Remarks
U1	1	For main motor spindle Inverter	Ue=380V- 460V~ 1.5kW 2HP	1	DELTA	VFD015B43	B IEC947-1
KM1	2,3	Relay contactor for main motor reverse	Res 5A 240VAC 5A 30VDC	1	IDCE	RY4S-U	DEC 255-0-2
KM2	2,3	Relay contactor for main motor forward	Coil 24VAC 50/60HZ	1	IDCE	RY4S-U	IEC 255-1 IEC 255-0-2
КМЗ	2,3	Magnetic contactor for coolantpump	Us=380V~ Ui 660V~ coll 60Hz 22V~ 4< <a>&gt; AC3Ith=AC1=25A</a>	1	TAIAN	CN-11	VDE 0660 IBC 947-4- BS 5424
KM4	1	Magnetic contactor for power supply	Ue=380V~ coil 50HZ 22V~ AC3Ith=AC1=35A 80HZ 24V~ Ui660V~3< <a>&gt;+1&lt;<a>&gt;</a></a>	1	TAIAN	CN-16	VDE 0660 IEC 947-4- BS 5424
KA1	3	Magnetic contactor for brake	Ue=22V~ Ith=6A 4< <a>&gt;</a>	1	TAIAN	RAN-4	VDE 0660 IBC 947-4- BS 5424
FU1		JULIAN DI LIKO	10m/mx38m/m				DS 3424
FU2	1	Fuse boxs	100KA	1	LEGRAND	133-10	IEC 269-2
FU3	÷		500V aM25A				
FU4	1	Fuse box	20mm 250V 1A	1	WAGO	282-122	VDE 0660 IEC 947
FU5	1	Fuse box	20mm 250V 1A	1	WAGO	282-122	VDE 0660 IEC 947
FU6	1	Fuse box	20mm 250V 4A	1	WAGO	282-122	VDE 0660 IEC 947
FR2	2,3	Thermal overload relay for coolantpump	380V: 0.18-0.24 A 0.19 A 220V: 0.24-0.38 A	1	TAIAN	RHN-10	VDE 0660 IEC 292-1 BS 4941
QS1	1	Main power switch	Ui 380V~	1	KLOCKNER MOELLER	P1-25/V/SVB	VDE 0660
HLI	3	Pilot light	22ø VCH24V	1	TELEMECANIQUE	XB2-BV63	VDE 0880 IEC 947-5-1 EN 60947-5-
TC1		Control circuit Transformer	Prim 220V/380V Sec. 22V,24V,150VA	1	TAIAN	TA-300	DI 00841 3
SA1		Selecting switch	22ø 600V 10A	1	TELEMECANIQUE	XB2-BD21	VDE 0660 IEC 947-5-1 EN 60947-5-
SB1		Off hand switch Emergency	22ø 600V 10A	1	TELEMECANIQUE	XB2-BS542	VDE 0680 IDC 947-5-1 EN 60947-5-
SB2		Push button switch (jogging switch)	22ø 600V 10A	1	TELEMECANIQUE	XB2-BA21	VDE 0860 IEC 947-5-1 EN 60947-5-
SB3	1	Push button switch (power supply off)	22ø 600V 10A	1	TELEMECANIQUE	XB2-BA21	VDE 0660 IEC 947-5-1 EN 60947-5-
SB4		Push button switch (power supply on)	22ø 600V 10A	1	TELEMECANIQUE	XB2-BA21	VDE 0660 TEC 947-5-1 EN 60947-6-
SQ1	_	Chuck guard switch	500V 6KV 10A	1	ELEMECANIQUE		VDE 0660 IEC 947-5-1 EN 60947-5-1
SQ2	33 1	Limit switch Endcover safety switch	500V 6KV 10A		KLOCKNER MOELLER		VDE 0660 IEC 947
SQ3	2	Limit switch for brake	250V 15A	1	OMRON	Z15GD-B	EN 60947
SQ4	3	Limit switch for main motor forward	250V 15A	1	OMRON	Z15GD-B	
SQ5	3	Limit switch for main motor reverse	250V 15A	1	OMRON	Z15GD-B	
M1	2	Squirrel-cage motors Foot-mounted	50kz,220/360V 1400 rev/min class E insulation 100L type ASEC, 1.5kv	1	SEING	ASEC	
MS		Coolantpump	50/60Hz,220/400V 2850/3400 rev/min type MT, 0.1kW	1 1	MING YIH	MT	

Para	ımeter Setti	ng				For DELTA	Invertor	
		t during operation.				*:Twice the value	for 460V class.	
Paramete	ers Evolunation	Setting	Factor	Param	eters	Explanation	Setting	Factory
A type B ty	pe		Setting	A lype B	2-01		d2: Master frequency determined by	Setting
Group (	): User Parameters			1 10	72-01		external terminal, STOP key disable.	
	00 Identity Code of Drive	Read-Only	TH	1			d3: Moster frequency determined by	1
00-	01 Rated Current Display	Read-Only					RS-485 communication interface, STOP	
	02 Parameter Reset	d10: reset parameter to factory settir	nd 0	1 1			key enable.	
00-	03 Start-up Display of AC Drive	d0: F (setting frequency)	0				d4: Master frequency determined by RS-485 communication interface, STDP	
		d1: H (actual frequency) d2: u (user-defined unit)	-				kewdisable.	
	*	d3: Multi Function Display	-	0	2-02	Stop Method	d0: Ramp Stop; E.F. coast stop	00
		d4: FWD/REV					d1: Coast Stop; E.F. coast stop	
00-	04 Content of Multi Function	d0: Display output current (A)	0				d0: Romp Stop; E.F. romp stop	-
	Display	d1: Display counter value (C) d2: Display process operation (1. tt)	-	71 0	2_03	PWM Carrier Frequency	d1: Coast Stop; E.F. ramp stop 0.75kW to 3.7kW (1 to 5 HP): d1 to	12
		d3: Display DC-BUS voltage (U)	-	11 0	2-00	I was control i requestey	d15	12
		d4: Diaplay output voltage (E)					5.5kW to 18.5kW (7.5 to 25 HP): d1	9
		d5: Output power factor angle (n.)					to d15	_
1 1	,	d6: Display output power (kW)	-				22kW to 45kW (30 to 60 HP): d1 to	9
100	00 11 - 0.6- 10- (6.1-1 )/-	d7: Display actual motor speed	1.00	1 1			55kW to 75kW (75 to 100 HP): d1 to	6
100-1	D5 User-Defined Coefficient K* D6 Software Version	Read-only	3.10				d9	1
	07 Password Input	10 to 65535	6	0	2-04	Reverse Operation	dO: Enable REV	00
00-0	08 Password Setting	0 to 65535	6	1			d1: Disable REV	
00-0	09 Control Methods	d0: V/F control	0	0	2-05	2-wire/3-wire Operation Control Mode Selection	d0: 2-wire Operation Control Mode (1)	- 00
		d1: V/F control + PG d2: Vector Control	-			CONTROL MODE SCIECTION	d1: 2-wire Operation Control Mode (2) d2: 3-wire Operation Control Mode	00
		d3: Vector Control + PC	-	0	2-06	Line Start Lockout	do: Disable	0
		SO. YOUR BUILD I TO				Diff Other Domost	d1: Enable	
	Basic Parameters			0.	2-07	Loss of AC1	dO: Decelerate to 0 Hz	0
03   01-0	00 Maximum Output Freq.	50.0 to 400 Hz	94				d1: Stop immediately and display "EF" d2: continue operation by last	
04 01-0	(Fo. Max) D1 Maximum Voltage Frquency	0.1 to 400 Hz	50	1 1			frequency command	
04  01-0	(Base Freq)(Fmax)	0.1 10 400 112	30				Troquette Continue	
05 01-0	02 Maximum Output Voltage	230V series: 0.10V to 255.0V	400					-
	(Vmax)	460V series: 0.10V to 510.0V		Group	3	Output Function Pa		
06 01-0	03 Mid-Point Frequency (Fmid)		10	0.	3-00		dO: Not Used	08
07 01-0	04 Mid-Point Voltage (Vmid)	230V: 0.1V to 255V 460V: 0.1V to 510V	84			(Rekry Output)	d1: AC Drive Operational d2: Max. Output Freq. Attained	
08 01-0	05 Minimum Output Frequency	0.10 to 400.00 Hz	1.5				d3: Zero speed	
	(Fmin)	3,10 33 100,00 112		0.		Multi-Function Output 2	d4: Over Torque	01
09 01-0	06 Minimum Output Voltage	230V series: 0.1V to 255V	20			(Photocoupler Output)	d5: Base-Block (B.B.)	
01.4	(Vrnin) 07 Upper bound of freq.	460V series: 0.1V to 510V	3.4	1			d6: Low Voltage Detection d7: Ac Drive Operation Made	
	07 Upper bound of freq.	1 to 110% 0 to 100%	00	0.	3-02	Multi-Function Output 3	d8: Fault Indication	02
	09 Accel Time 1 +	0.1 to 3600.0 sec	2		0 02	man vanousi adque s	d9: Desired Freq. Attained	
.11 01-	10 Decel Time 1 *	0.1 to 3600.0 sec	2				d10: PLC Program Running	
			0.06\0.0	0	7 07	Multi-Function Output 4	d11: PLC Program Step Complete d12: PLC Program Complete	20
13 01-1	12 Decel Time 2 * 13 Jag accel/decel Time *	0.1 to 3600.0 sec 10	1.0	10.	J-W	MURITUREUM COOPER 4	d13: PLC Program Operation Pause	20
23 01-1	14 Jog Frequency *	0.10 Hz to 400.00 Hz	6.00				d14: Terminal Count Value Attained	
	15 Auto Accel/Decel	d0: Linear Accel/Decel	00				d15: Preliminary Count Value Attained	
		d1: Auto Accel, Linear Decel			1		d16: Auxiliary Motor No. 1	
		d2: Linear Accel, Auto Decel	-				d17: Auxiliary Motor No. 2 d18: Auxiliary Motor No. 3	
		d3; Auto Accel/Decel d4; Linear Accel/Decel Stall,	-				d19: Heat Sink Overheal Warning	
		Prevention during deceleration					d20: AC Drive Ready	
15 01-1	16 S-Curve in Accel	00 to 07	00				d21: Emergency Stop Indication	
15 01-	17 S-Curve in Decel	00 to 07	00				d22: Desired Frequency Attained 2	
		0.1 to 3600.0 sec	10.0				d23: Software Break Singal d24: Zero Speed Output Singal	
		0.1 to 3600.0 sec 0.1 to 3600.0 sec	10.0	0.	3-04	Desired Freq. Altoined	0.00 to 400.00 Hz	0.00
		0.1 to 3600.0 sec	10.0				d0: Output frequency	0.00
101-1	ET DOOR THIN T						d1: Output current	
	Operation Method P	arameters	1 4				d2: Output voltage	
02-0	OO Source of Frequency	d0: Digital keypad	1 1				d3: Frequency command	
		d1: 0 to +10V from AVI d2: 4 to 20mA from ACI	- 1				d4: Motor output speed d5: Output power factor	
		d3: Potentiometer control	1 1	0.	3-06		1 to 200%	100
		(-10 to +10Vdc)		0.	3-07	Digital Output Gain *	1 to 20	01
		d4: RS-485 communication Interface		03	3-08	Terminal Count Value	0 to 65500	0
02-0		dO: Determined by digital keypad	2				0 to 65500	0 00
	Command	d1: Moster frequency determined by external terminal, STOP key enable.		10.	)-1U	Desired Freq. attained 2	0.00 to 400.00 Hz	0.00
		CALCITUS BUILDING JIVI BC) CHOICE						

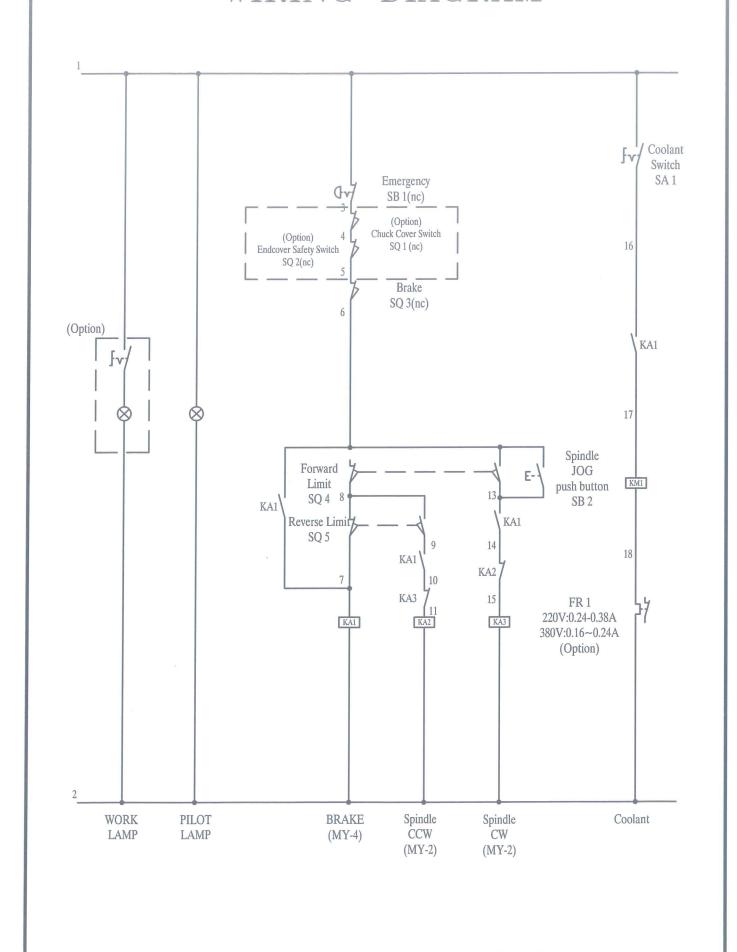
Pa	rar	neter Sett	ing				For DELTA	invertor	
			set during operation.				*:Twice the value		
argi	meters B type	Evolanation	Setting	Factory	Para A type	meter: e B type	Expiditoti	Selling	Facto Setti
						05-21	Time Duration Step 5	00 to 65500 sec	00
Grou		Input Function Po	arameters	T 10	-		Time Duration Step 6 Time Duration Step 7	00 to 65500 sec 00 to 65500 sec	00
	04-00	Potentiometer Bias Frequency #	0.00 to 350 Hz	10	-	05-23	Time Duration Step 8	00 to 65500 sec	00
	04_01	Potentiometer Bias	d0: Positive Bias	0		05-25	Time Duration Step 9	00 to 65500 sec	1 00
	04-01	Polarity *	d1: Negative Bias	1		05-26	Time Duration Step 10	00 to 65500 sec	00
	04-02	Potentiometer Bias	1 to 200%	100		05-27	Time Duration Step 11	00 to 65500 sec	00
		Gain *					Time Duration Step 12	00 to 65500 sec	00
	04-03	Potentiometer Reverse	d0: Forward Motion Only	0			Time Duration Step 13	00 to 65500 sec	00
		Motion Enable	d1: Reverse Motion Enable				Time Duration Step 14	00 to 65500 sec	00
1.0	01 01	W II' E I' I I	d2: Forward and Reverse Motion Enable	0	-	103-31	Time Duration Step 15	00 to 65500 sec	00
16 17	104-04	Multi-Function Input	d0: Parameter Disable d1: Multi-Step Speed Command 1	1	-	-			+
1.7		Terminal 1 (MK), MI1)	d2: Multi-Step Speed Command 2	2					
18	04-05	Multi-Function Input	d3: Mutti-Step Speed Command 3	3	Grou	D 6	Protection Paramet	ers	
19	07 03	Terminal 2 (MI2)	d4: Multi-Step Speed Command 4	4	25	06-00	Over-Voltage Stall	d0: Disable	1 0
		Torrierd E (MIE)	d5: Reset	5			Prevention	d1: Enable	1
	04-06	Multi-Function Input	d6: Accel/Decel Speed Inhibit	6	26	06-01	Over-Current Stall	20 to 250%	200
		Terminal 3 (MI3)	d7: First or Second Accel/Decel Time				Prevention during Accel		
			Selection		27	06-02	Over-Current Stall	20 to 250%	200
	04-07	Multi-Function Input	d8: Third or Fourth Accel/Decel Time				Prevention during		
	01.00	Terminal 4 (MI4)	Selection	-		06 57	Operation Over-Torque Detection	d0: Disable	00
	04-08	Multi-Function Input	d9: External Base Block (N.C.) Input			00-03	Mode	d1: Enable during constant speed	1 00
		Terminal 5 (MI5)	d10: External Base Block (N.O.) Input d11: Increase Master Frequency				Mode	operation and continues until the	
-	04-09	Multi-Function Input	d12: Decrease Master Frequency					continuouslimit (Pr.08-05) is reached.	
	UT UJ	Terminal 6 (MI6)	d13: Counter Reset					d2: Enable during constant speed	1
		Torring o (milo)	d14: Run PLC Program					operation and halted after detection.	
			d15; Pause PLC					d3: Enable during Accel and continues	
			d16: Auxiliary Motor No.1 Output Failure					before Continuous Output Time Limit	
			d17: Auxiliary Motor No.2 Output Failure					(Pr.06-05) is reached.	
		5	d18: Auxiliary Motor No.3 Output Failure					d4: Enable during Accel and halted	
			d19: Emergency Stop (NO)		-	06 74	Over-Torque Detection	after Over-Torque detection.	150
			d20: Emergency Stop (NC) d21: Analog Output Frequency AVI/ACI			00-04	Level	3U 10 2UU%	150
			d22: Analog Output Frequency AVI/AUI			06-05	Continuous Output Time	0.1 to 60.0 Sec	0.1
			d23: Operation Command			00 00	Limit	0.1 10 00.0 300	0.1
			Keypad/external Terminal	1		06-06	Electronic Thermal	d0: Reduce Torque Motor	02
			d24: Auto/Linear Accel/Decel Selection				Overload Relay	d1: Constant Torque Motor	
		Digital Terminal Input	D01 to d20m sec	01				d2: Inactive	
		Delay Time					Electronic Thermal	30 to 600 Sec	60
	- 1		1 21 0 2			00 20	characteristic * Present Fault Record	d0: No Fault occurred	00
rou	05 00	1st Step Speed Freq.	and PLC Parameters  [0.00 to 400.00 Hz	0.00		00-00	Present rount record	d1: Over Current (oc)	W
-	05-00	2nd Step Speed Freq.	0.00 to 400.00 Hz	0.00				d2: Over Voltage (ov)	1
-	05-02	3rd Step Speed Freq.	0.00 to 400.00 Hz	0.00				d3: Over Heat (oH)	
	05-03	4th Step Speed Freq.	0.00 to 400,00 Hz	0.00				d4: Over Load (oL)	1
	05-04	5th Step Speed Freq.	0.00 to 400.00 Hz	0.00				d5: Over Load (oL1)	
	05-05	6th Step Speed Freq.	0.00 to 400.00 Hz	0.00		06-09	Second Most Recent	d6: External Fault (EF)	
	05-06	7th Step Speed Freq.	0.00 to 400.00 Hz	0.00				d7: IGBT Protection (acc)	
		8th Step Speed Freq.	0.00 to 400.00 Hz	0.00				dB: CPU Fault (cF3)	
		9th Step Speed Freq.	0.00 to 400.00 Hz	0.00		00 00	Third Ward Classed	d9: Hardware Protection Failure (HPF)	. 0
-	05-09	10th Step Speed Freq.	0.00 to 400.00 Hz	0.00		00-10	Third Most Recent Fault Record	d10: Current exceed during Acceleration (oca)	. 0
-	05 11	11th Step Speed Freq. 12th Step Speed Freq.	0.00 to 400.00 Hz 0.00 to 400.00 Hz	0.00			rduit Record	d11: Current exceed during	
		13th Step Speed Freq.	0.00 to 400.00 Hz	0.00				Deceleration (ocd)	
		14th Step Speed Freq.	0.00 to 400.00 Hz	0.00				d12: Current exceed during Steady	
		15th Step Speed Freq.	0.00 to 400.00 Hz	0.00				Stale (ocn)	
		PLC Mode	d0: Disable PLC Operation	00				d13: Ground Fault (CF)	
			d1: Execute one program cycle					d14: Lv	
			d2: Continuously execute program					d15: CF1	
	-		cycles			- 1	Fourth Most Recent	d16: CF2	
1			d3: Execute one program cycle step				Foult Record	d17: Bose Block (b.b.)	
			by step					d18: oL2	
			d4: Continuously execute one program	- 1				d19: CFA d20: codE	
-	05-16	PLC Forward/Reverse	cycle step by step  00 to 32767 sec (0:FWD 1:REY)	00				d21: EF1 (External Emergency Stop)	
		Motion	ער נו עבוטו שפר לחוואה ויווריו	~		06-12	Over-voltage Stall Level	230V Series: 330V to 410V	390
-		Time Duration Step 1	00 to 65500 sec	00	1		ronago oran coron	460V Series: 660V to 820V	780
1			00 to 65500 sec	00				2201	
	05-18	time puration Step 2	00 10 02000 200						
		Time Duration Step 2 Time Duration Step 3	00 to 65500 sec	00					

Po	ıraı	meter Setti	ng					invertor	
Poro	meter:	Evalenation	st during operation.  Setting	Factor	Pora A type	meters B type	*:Twice the value  Explanation	Setting	Factor Settin
					CHOL	ın 0ı	Communication	taram etere	
Grou		Motor Parameters  Motor Rated Current *	30 to 120%	100	Grot	109-00	Communication F Communication Address *	11 to 254	11
		Motor No-load Current *	0 to 90%	40		09-01	Transmission Speed	d0: Baud Rate 4800bps	11
54		Tarque Compensation *	0 to 10	6				d1: Baud Rate 9600bps	
55		Slip Compensation *	0.00 to 3.00	1			1	d2: Baud Rate 19200bps	
		Number of Motor Poles	02 to 10	04				d3: Baud Rate 38400bps	
	07-05	Motor Auto Detection	dO: Disable	00	1	09-02	Transmission Fault	dO: Warn and keep Operation	0
	07.00		d1: Enoble	0.00		1	Treatment	d1: Warn and Ramp to Stop d2: Warn and Coast to Stop	-
	07-06	Motor Line-to-Line Resistance (R1)	0.00 to 655.35	0.00				d3: No warning and keep Operation	-
	07-07	Equivalent Rotor	00 to 200%	100	_	09-03	Overtime Detection	d0: Disable	1
	0, 0,	Resistance (R2)		1.00				d1: Enable	1 '
	07-08	Motor Rated Slip	0 to 20 Hz	3		09-04	Communication Protocol	d0:+7, N, 2 (Modbus, ASCII)	0
	07-09	Slip Compensation Limit	Ω to 250%	200				d1: 7, E, 1 (Modbus, ASCII)	
	07-10	Vector Control Current Compensation Limit	d0.0 to d2.0	1.5				d2: 7, 0, 1 (Modbus, ASCII) d3: 8, N, 2 (Modbus, RTU)	
				1				d4: 8, E, 1 (Modbus, RTU) d5: 8, 0, 1 (Modbus, RTU)	
Prou	108-NO	Special Parameters DC Braking Current Level	10 to 100%	60	Grou	p 10:	: PID Control Parar	neters	
29	08-01	DC Braking Time during	0.0 to 60.0 Sec	0.0		10-00	Input Terminal for	d0: Inhibit PID operation	00
		Start-Up DC Braking Time during	0.0 to 60.0 Sec	2			Frequency	d1: Input negative PID feedback from external terminal (AVI) 0 to +10V	
-	00.07	Stopping	0.00 1 100.00 11	00				d2: Input negative PID feedback from	1
31	08-03	Start-Point for DC Braking	0.00 to 400.00 Hz d0: Stop Operation after Momentary	90				external terminal (ACI) 4 to 20mA d3: Input positive PID feedback from	-
32	08-04	Momentary Power Loss	Power Loss	U			4	external terminal (AVI) 0 to +10V	
			d1: Continues after Momentary Power					d4: Input positive PID feedback from	1
			Loss, speed search starts with Master					external terminal (ACI) 4 to 20mA	
			Frequency			10-01	Gain over Frequency Input	d0.01 to d10.0	1.00
			d2: Continues after Momentary Power			10-02	Proportional Gain (P)	d0.0 to d10.0	1.0
			Loss, speed search starts with Minimu	ф		10-03	Integral Gain (1)	d0.00 to d100.00 sec	1.00
			Output Frequency.			10-04	Derivative Control (D)	d0.00 to d1.00 sec	0.00
		Maximum Allowable . Power Loss Time	0.3 to 5.0 sec	2.0			Upper Bound for Integral Control Derivative Filter Time	0 to 110%	100
34	08-06	B.B. Time for Speed Search	0.1 to 5.0 sec	4			Constant	0.0 to 2.5 sec	0.0
35	08-07	Maximum Speed Search	30 to 200%	190		10-07	PID Output Freq Limit Feedback Singal Detection	0 to 110% 0.0 to 3600.0 sec	100
36	08-08	Current Level Skip Frequency 1 Upper	0.00 to 400.00 Hz	0.00			time		
		Bound		0.00			Transmission Fault	d0: Warn and keep operation	0
	08-09	Skip Frequency 1 Lower	0.00 to 400.00 Hz	0.00			Treatment	d1: Warn and RAMP to stop	-
	00 10	Skip Frequency 2 Upper	0.00 to 400.00 Hz	0.00	-	10_10	PG Pulse Ronge	d2: Warn and COAST to stop d1 to d40000	600
	UD-10	Bound	0.00 @ <del>1</del> 00.00 nz	0.00	-	10-10	PG Input	d0: Disable PG	000
-	08-11	Skip Frequency 2 Lower	0.00 to 400.00 Hz	0.00		/ 11	e se impair	d1: Single phase	30
	00 11	Bound	0.00 (0 100.00 112					d2: Forward / Counterclockwise rotatio	
	08-12	Skip Frequency 3 Upper	0.00 to 400.00 Hz	0.00				d3: Reverse / Clockwise rotation	
		Bound				10-12	Proportional Speed control	d0 to d20	0.1
	08-13	Skip Frequency 3 Lower	0.00 to 400.00 Hz	0.00		10 47	(P)	1001-1000	4.0
	00 11	Bound	0 10 10	0	$\vdash$	10-13	Integral Speed Control (1) Speed Control Output	0.0 to 100.0 00 to 20.00 Hz	1.0
		Auto Restart After Fault Auto Energy Saving	0 to 10 d0: Disable	0		10-14	Frequency Limit	מי מי בט.טע חב	10.00
	00-13	Multo Likingy Juning	d1: Enable	"		10-15	PG Detected Output	d1 to d500	500
_	08-16	AVR Function	dQ: AVR Function Enable	0			Renewal Time	47 10 0000	000
			d1: AVR Function Disable						
			d2: AVR Function Disable for Decel		Grou	p 11:	Fan & Pump Con	trol Parameters	
	08-17	Dynamic Braking Voltage	230V: 370 to 430V	380		11-00	V/F Curve Selection	d0: V/F Curve determined by Pr.01-	0
			460V: 740 to 860V	760				00 to Pr.01-06	
	00.10		dO: Speed Search Starts with Last	.0				d1: 1.5 Power Curve	
	08-18	Base-block Speed Trace	Fraguency Commend		1 1			d2: 1.7 Power Curve	
	08-18	Base-block Speed Trace	Frequency Command		1				
	08-18	Base-block Speed Trace	d1: Speed Search Starts with Minimum					d3: Square Curve	
		•	d1: Speed Search Starts with Minimum Output Frequency			11-01	Start Frequency of the	d4: Cube Curve	0.00
		Base-Dlock Speed Trace Speed Search	d1: Speed Search Starts with Minimum Output Frequency d0: Speed Search Disable	0			Start Frequency of the Auxiliary Motor		0.00
		•	d1: Speed Search Starts with Minimum Output Frequency				Auxiliary Motor	d4: Cube Curve 0.00 to 120.00 Hz	0.00
		•	d1: Speed Search Starts with Minimum Output Frequency d0: Speed Search Disable			11-02	Auxiliary Motor Stop Frequency of the Auxiliary Motor	d4: Cube Curve 0.00 to 120.00 Hz 0.00 to 120.00 Hz	
		•	d1: Speed Search Starts with Minimum Output Frequency d0: Speed Search Disable			11-02	Auxiliary Motor Stop Frequency of the Auxiliary Motor Time Delay before	d4: Cube Curve 0.00 to 120.00 Hz	
		•	d1: Speed Search Starts with Minimum Output Frequency d0: Speed Search Disable			11-02	Auxiliary Motor Stop Frequency of the Auxiliary Motor	d4: Cube Curve 0.00 to 120.00 Hz 0.00 to 120.00 Hz	0.00

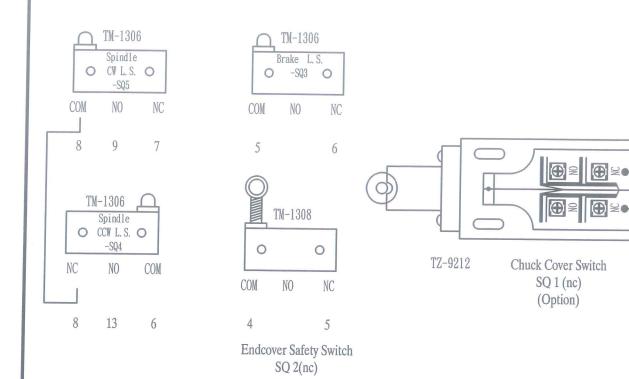
## WIRING DIAGRAM

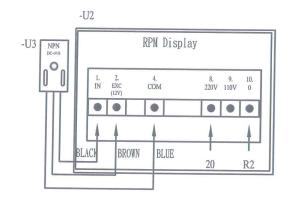


# WIRING DIAGRAM

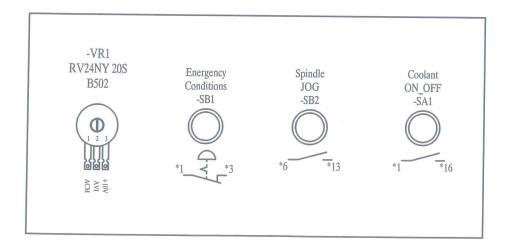


# WIRING DIAGRAM









TY.	PE:		MACHINE SERIAL NO.					
NO	NO. SUBJECT OF MEASUREMENT		ILLUSTRATION	PERMISSIBLE ERROR	MEASUREI ERROR			
1.	Levelling of machine	(a) in longitu— dinal direction	(a)	±0.04 mm/m				
		(b) in transverse direction	b a (b)	±0.04 mm/m				
2.	Taper of spindle runs true		300 mm long	Position A: 0.01 mm				
				Position B: 0.02 mm				
3.	Spindle parallel with traverse of carriage	(a) in vertical plane	a & b	(a) 0.02/ 300 mm				
		(b) in horizontal plane		(b) 0.02/ 300 mm				
' .	Upper Slide (Paralleli Slide Longitudinal Mo the Spindle Axis)			0.01/150 mm				
	Axis of centres paral with bed in vertical		A B	0.02/ 300 mm				

6.	Tailstock spindle parallel with carriage guides (carriage traverse)	(a) in vertical plane  (b) in horizontal plane		b b	(a) 0.02/ 150 mm (b) 0.01/ 150 mm	
7.	Centring register of spindle runs true		-		0.01 mm	
8.	Spindle for axial floa and ture running of of spindle flange		_		0.015 mm	
9.	Centre runs true		_		0.015 mm	
10.	Working accuracy of cylindrical turning	lathe on	fin		0.015mm (cylindricity) (D=25mm ~50mm)	
СНІЕ	F ENGINEER :			INSPECTING ENGINE	CER :	

#### 1340VS

Parameters	Explanation	參數功能	<b>Factory Setting</b>
00-07	Password Input	參數保護密碼輸入	06
00-08	Password Setting	參數保護密碼設定	06
01-00	Maximum Output Freq. (Fo,max)	最大操作頻率	77
01-03	Mid-Point Frequency (Fmid)	中間頻率設定	9
01-04	Mid-Point Voltage (Vmid)	中間電壓設定	40
01-05	Minimum Output Frequency (Fmin)	最低頻率輸出設定	1.5
01-06	Minimum Output Voltage (Vmin)	最低輸出電壓設定	20
01-09	Accel Time 1	第一加速時間	2
01-10	Decel Time 1	第一減速時間	2
02-00	Source of Frequency Command	頻率指令來源設定	1
02-01	Source of Operation Command	運轉指令來源設定	2
02-03	PWM Carrier Frequency	載波頻率設定	12
04-00	Potentiometer Bias Frequency	類比輸入頻率偏壓	9.8
06-00	Over-Voltage Stall Prevention	過電壓失速防止	0
06-01	Over-Current Stall Prevention during Accel	加速中過電流失速 防止	200
06-02	Over-Current Stall Prevention during Operation	運轉中過電流失速 防止	200
07-02	Torque Compensation	轉矩補償增益	6
07-03	Slip Compensation	轉差補償增益	1
08-00	DC Braking Current Level	直流制動電流準位	60
08-03	Start-Point for DC Braking	直流制動的起始頻 率	78
08-06	B.B. Time for Speed Search	速度追蹤時間	4
08-07	Maximum Speed Search Current Level	速度追蹤最大電流	190

## **DELTA** inverter parameter

Parameters	Explanation	参數功能	<b>Factory Setting</b>
00-07	Password Input	參數保護密碼輸入	06
00-08	Password Setting	參數保護密碼設定	06
01-00	Maximum Output Freq. (Fo,max)	最大操作頻率	77
01-03	Mid-Point Frequency (Fmid)	中間頻率設定	9
01-04	Mid-Point Voltage (Vmid)	中間電壓設定	40
01-05	Minimum Output Frequency (Fmin)	最低頻率輸出設定	1.5
01-06	Minimum Output Voltage (Vmin)	最低輸出電壓設定	20
01-09	Accel Time 1	第一加速時間	2
01-10	Decel Time 1	第一減速時間	2
02-00	Source of Frequency Command	頻率指令來源設定	1
02-01	Source of Operation Command	運轉指令來源設定	2
02-03	PWM Carrier Frequency	載波頻率設定	12
04-00	Potentiometer Bias Frequency	類比輸入頻率偏壓	9.8
06-00	Over-Voltage Stall Prevention	過電壓失速防止	0
06-01	Over-Current Stall Prevention during Accel	加速中過電流失速防止	200
06-02	Over-Current Stall Prevention during Operation	運轉中過電流失速 防止	200
07-02	Torque Compensation	轉矩補償增益	6
07-03	Slip Compensation	轉差補償增益	1
08-00	DC Braking Current Level	直流制動電流準位	60
08-03	Start-Point for DC Braking	直流制動的起始頻 率	78
08-06	B.B. Time for Speed Search	速度追蹤時間	4
08-07	Maximum Speed Search Current Level	速度追蹤最大電流	190



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